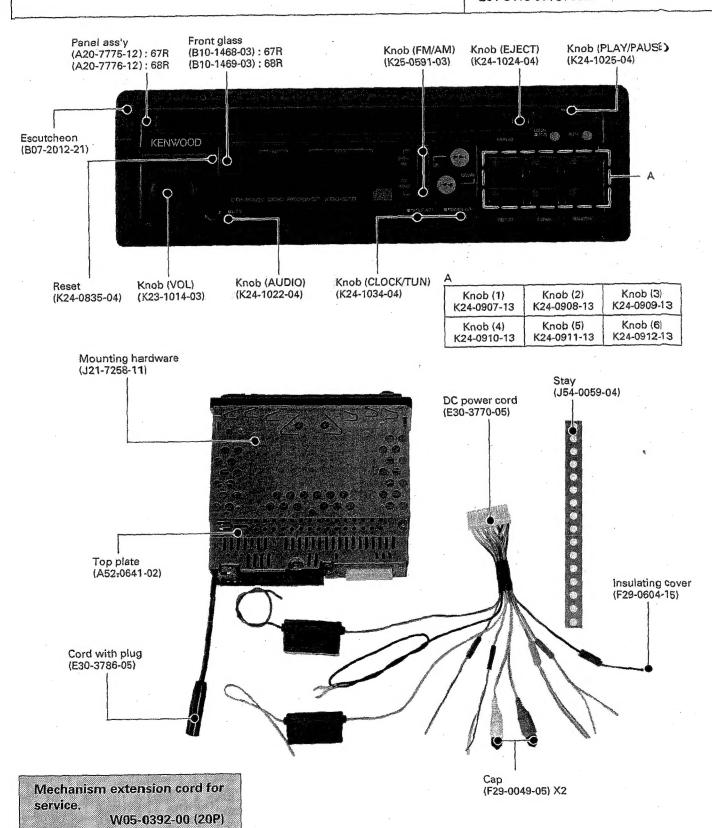
CD RECEIVER

KDC-67R/68R SERVICE MANUAL

KENWOOD

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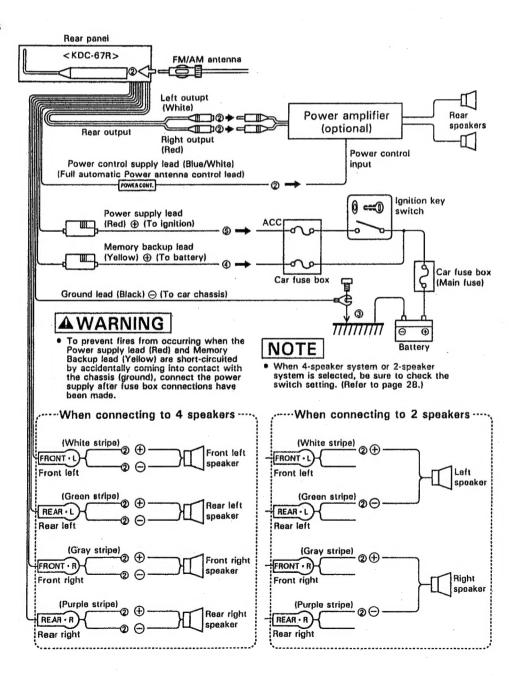


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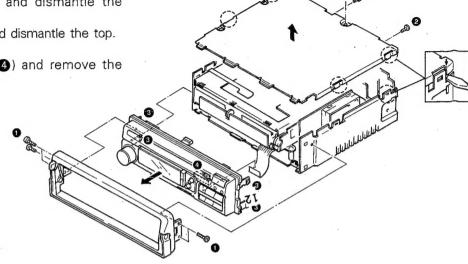
Connections



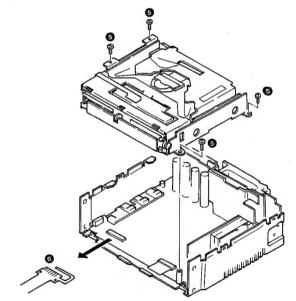
DISASSEMBLY FOR REPAIR

Disassembly for repair

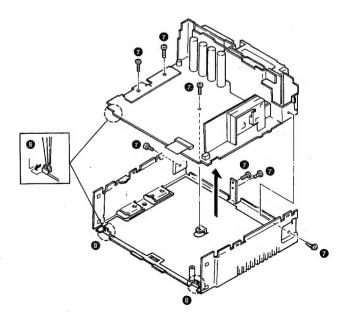
- 1. Remove the 5 screws () and dismantle the handle.
- 2. Remove the 3 screws (2) and dismantle the top.
- 3. Disengage the 5 claws (3).4. Disconnect the connector (4) and remove the front panel.



- 5. Remove the 4 screws (6).
- 6. Disconnect the connector (6) and take out the mechanism assembly.

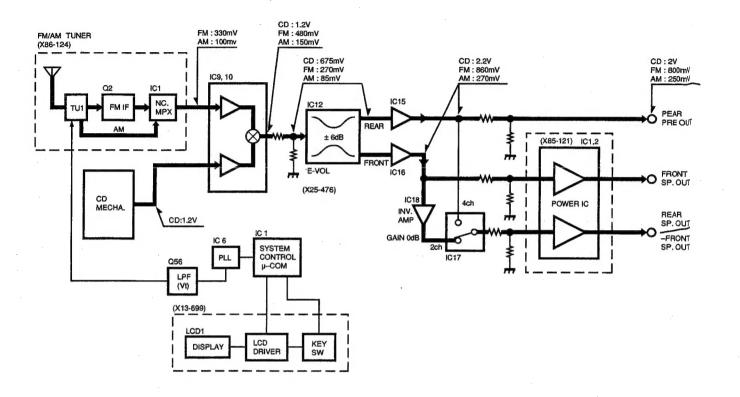


- 7. Remove the 7 screws (3).
- 8. Bend and disengage the 2 lugs on the metallic holder fixing the circuit board (8).

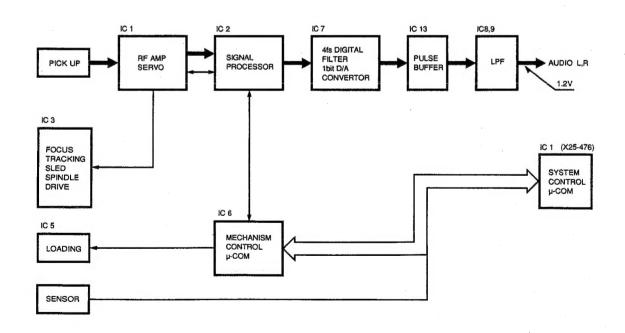


BLOCK/LEVEL DIAGRAM

Block diagram



CD mechanism



CIRCUIT DESCRIPTION

1. Description of components

1-1. Electric unit (X25-4760-10)

Ref No.	Use / Function	Operation / Condition					
IC1	System controller						
IC3	Reset IC	Prevents system controller malfucntion ("L" below 3.7V)					
IC4	3-terminal 5V regulator	5V power supply for microcomputer, digital circuitry and mechanism servo.					
		(A 3-terminal) IC with small power consumption : ordinary products cannot be used.)					
1C5	AVR driver	8V AVR.					
IC6	PLL	Switches between FM+B, AM+B and LW/MW at output ports.					
IC9, 10	CD/TUNER SW	Switches inputs with switching opamp. Determined level distributions of CD and tuner					
IC11	Volume buffer	Voltage follower.					
IC12	Electronic volume/tone IC	Tone control, loudness (low frequencies only), volume, balance, fader.					
IC13, 14	Tone amp fader-buffer	Voltage-followers.					
IC15	Pre-out buffer preamp (When 4CH is selected)	In 4CH operation, functions as the rear preamplifier supplying inputs to power amplifie					
IC16	Preamp	Front preamplifier supplying inputs to power amplifier.					
IC17	2CH/4CH analog SW	In 2CH operation, switched to front signals inverted by IC18. In 4CH operation,					
		switched to rear signals.					
IC18	Inverter amp	In 2CH operation, inverts front signals and supplies them to power amplifier inputs.					
IC19	1/2 Vcc buffer	Outputs 1/2 of 8V for use as reference voltage of audio circuitry.					
Q1, 28, 38	Muting	Muting driver. When reset is applied, Q28 turns driver Q1 ON. In case of momentary					
		power failure, Q37 and Q38 turns driver Q1 ON.					
Q2, 3	MUTE	Muting driver receiving instructions from system controller.					
Q4	AVR	8V output.					
Q5	14.4V SW	Interlocked with µ-COM power ON.					
Q6, 7	Servo +B AVR	Servo power supply, 7.6V output.					
Q8, 9	Illumination AVR	Illumination power supply. 10.5V output.					
Q10~13	Illumination SW	Switches between amber/green.					
Q14	Acc detector	Collector goes "L" when Acc is ON.					
Q15, 37	BU detector	Collector goes "L" when BU voltage is connected.					
Q16	P-COM, P-ANT	P-COM and P-ANT driver.					
Q17, 18	P-COM	P-COM protection.					
Q19	P-COM ON/OFF						
Q20, 21	Power amp standby	Turns ON/OFF standby port of power IC.					
Q22, 23	Rotary encoder buffer	Converts rotary encoder output into level read by μ-COM input port.					
Q24 .	5V SW	Interlocked with μ-COM power ON.					
Q25							
Q26	CD/TUNER SW	Switches inputs to IC9 and IC10.					
Q27, 29	Reset	To reset μ-COM. μ-COM RESET port is turned "L" by panel RESET switch.					
Q31~36	Muting	Audio muting					
Q51	FM muting output	FM muting output turns SX meter output "LOW".					
Q52	AM SD output buffer	Low during reception.					
Ω53	FM S meter buffer	Emitter-follower.					
Q54	AFC SW	Collector is "L" during seek.					
Q55	FM SD output buffer	Low during reception.					
Q56	LPF	Used with both FM and AM.					
Ω58	FM +B ON/OFF						
Q59	AM +B ON/OFF						

CIRCUIT DESCRIPTION

Ref No.	Use / Function	Operation / Condition
D1, 2	Reverse connection protection	Protection diodes to prevent reverse current flow to GND in case of
		reverse connection of BU (D1) or ACC (D2).
D3	Reverse current prevention in case of	In case of momentary power failure, D3 prevents reverse current to prevent 5V power
	momentary power failure.	voltage drop.
D4	Reference voltage	Reference voltage of servo +B AVR.
D5	Reference voltage	Reference voltage of illumination +B AVR.
D6	Level shift	Sets Acc detection threshold level.
D7	Discharging	Discharges C20 by providing difference in constant at the time of ON/OFF.
D8	Discharging	Discharges C21 by providing difference in constant at the time of ON/OFF.
D9	Level shift	Sets BU voltage detection threshold level.
D10	Reverse current prevention	For the case in which receiving side of P-ANT has capacity.
D11	Discharging	Discharges C24 to release P-CON protection.
D12	Reverse current prevention	Prevents reverse flow of 14.4V toward 5V.
D13	Static protection	Prevents static electricity from applying reset.
D51	Temperature compensation	
D52	Constant voltage	Constant voltage of LPF current.

1-2. Switch unit (X13-6990-10)

Ref No.	Use / Function	Operation / Condition					
IC1	LCD driver	Controls LCD display.					
D3	Illumination LED	Back light of PLAY key.					
D7~12	Back light of preset keys (1 to 6).						
D15	Back light of PWR SW and clock or						
	Illumination or SDK.						
P1, 2	Illumination lamps (amber)	Back light of LCD, VOL and keys near lamps.					
D1	Illumination lamp LED						
D2 ·	Back light of EJECT.						
D4~6	Back light of LOCAL and AUTO.						
D13, 14	Back light of VOL.						
LCD	Liquid crystal display	Displays characters and numerals					

1-3. Tuner unit (X86-1240-10)

Ref No.	Use / Function	Operation / Condition				
Q1	LOCAL / DX SW	ON during LOCAL seek.				
Q2	IF AMP					
Q3	AM AGC (1st stage)	ON during seek.				
Q4	AM AGC (2nd stage)	Turned ON when Q3 goes ON.				
Q5	Muting	ON in turner reception.				
IC1	FM processor					

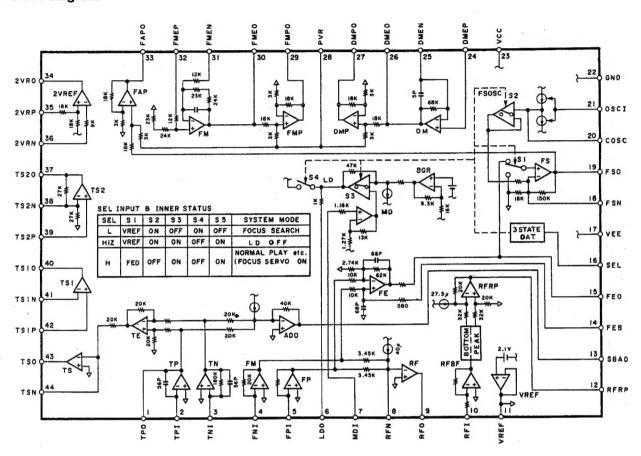
1-4. Power amplifler unit (X85-1210-10)

Ref No.	Use / Function	Operation / Condition
IC1, 2	Power amp	

CIRCUIT DESCRIPTION

2. RF amp/Servo: TA8191F (X32-2210) IC1

2-1. Block diagram



2-2. Terminal function (TA8191F)

2-2. Terminal function		SUOII	(IAOISIF)	
Pin No.	Symbol	1/0	Function	Remark
1	TPO	0	Sub-beam I-V amp (TP AMP) output terminal.	Connected to TPI via adjustment feedback resistor.
2	TPI	1	Sub-beam I-V amp (TP AMP) input terminal.	Connected to PIN diode F.
3	TNI	1	Sub-beam I-V amp (TN AMP) input terminal.	Connected to PIN diode E.
4	FNI		Main beam I-V amp (FN AMP) input terminal.	Connected to PIN diode A + C.
5	FPI	1	Main beam I-V amp (FP AMP) output terminal.	Connected to PIN diode B + D.
6	LDO	0	Laser diode amp (LD AMP) output terminal.	Connected to laser diode circuit.
7	HDI	1	Monitor photodiode amp (MP AMP) input terminal.	Connected to monitor photodiode.
8	RFN	1	RF amp (RF AMP) inverted input terminal.	Connected to RFO via feedback resistor.
9	RFO	0	RF amp (RF AMP) output terminal.	
10	RFI	1	RF ripple signal generator input terminal.	Connected to RFO via CR.
11	VREF	0	Reference voltage output terminal (+2.1V).	
12	RFRP	0	RF ripple signal output terminal.	
13	SBAD	0	Scratch detect signal output terminal.	
14	FEB	1	Focusing error balance adjustment input terminal.	Semi-fixed resistor for adjustment is connected.
15	FEO	0	Focusing error amp (FE AMP) output terminal.	Resistor for gain adjustment is connected.
16	SEL	1	Analog switch control signal input terminal.	
17	VEE	-	Power supply terminal.	Connected to GND.
18	FSN	1	Focus output amp (FS AMP) inverted input terminal.	Connected to FSO via feedback CR.
19	FSO	0	Focus output amp (FS AMP) output terminal.	
20	COSC	0	Capasitor connection terminal for focus search signal	CR are connected.
			generation.	

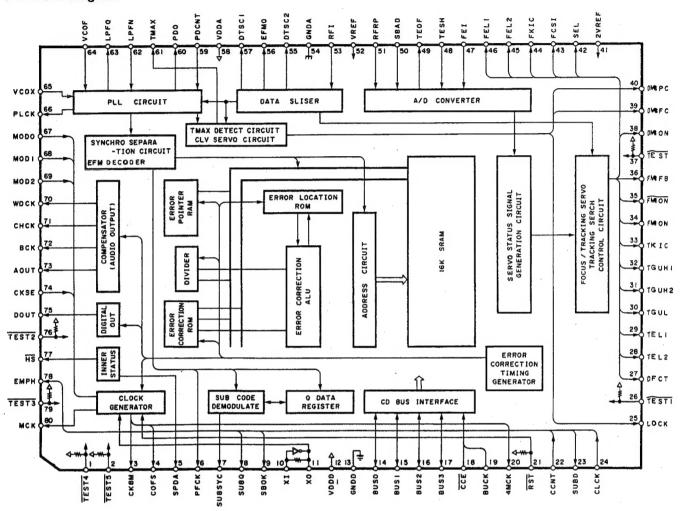
CIRCUIT DESCRIPTION

Pin No. Symbol		1/0	Function	Remark
21	OSCI	1	Built-in current supply control input terminal for focus	
			search signal generation.	
22	GND	-	Ground terminal.	
23	Vcc	-	Power supply terminal (+5V).	
24	DMEP	1	Disc motor amp (DM AMP) input terminal.	
25	DMEN	1	Disc motor amp (DM AMP) inverted input terminal.	
26	DMEO	0	Disc motor amp (DM AMP) output terminal.	
27	DMPO	0	Disc motor drive amp (DM AMP) output terminal.	
28	PVR	1	Drive amp reference voltage input terminal.	Connected to VREF.
29	FMPO	0	Feed motor drive amp (FMP AMP) output terminal.	
30	FMEO	0	Feed motor amp (FM AMP) output terminal.	
31	FMEN	1	Feed motor amp (FM AMP) inverted input terminal.	
32	FMEP	1	Feed motor amp (FM AMP) input terminal.	
33	FAPO	0	Focus actuator drive amp (FMP AMP) output terminal.	
34	2VRO	0	2VREF amp (2VREF AMP) output terminal.	Connected to 2VRP via external output Tr.
35	2VRP	1	2VREF amp (2VREF AMP) input terminal.	
36	2VRN	1	2VREF amp (2VREF AMP) inverted input terminal.	
37	TS2O	0	Tracking servo amp 2 (TS2 AMP) output terminal.	
38	TS2N	1	Tracking servo amp 2 (TS2 AMP) inverted input terminal.	
39	TS2P	1	Tracking servo amp 2 (TS2 AMP) input terminal.	
40	TS10	0	Tracking servo amp 1 (TS1 AMP) output terminal.	
41	TS1N	1	Tracking servo amp 1 (TS1 AMP) inverted input terminal.	Connected to TS10 via feedback CR.
42	TS1P	1	Tracking servo amp 1 (TS1 AMP) input terminal.	
43	TSO	0	Tracking output amp (TS AMP) output terminal.	
44	TSN	1	Tracking output amp (TS AMP) inverted input terminal.	Connected to TSO via feedback CR.

CIRCUIT DESCRIPTION

3. Signal processor: TC9236AF (X32-2210) IC2

3-1. Block diagram



3-2. Terminal function (TA9236AF)

Pin No.	Symbol	1/0	Function	Remark
1	TEST4	1	Test pin. Normally "H" or Open.	With pull-up resistor.
2	TEST5	_	Test pin. Normally "H" or Open.	With pull-up resistor.
3	CK8M	0	8M clock output terminal.	
4	COFS	0	Correction frame cycle signal output terminal. 7.35kHz.	
5	SPDA	0	Processor status signal output terminal. Correction processing check result, memory	
			buffer capacity, etc.	
6	PFCK	0	Playback frame cycle signal output terminal. 7.35kHz.	
7	SUBSYC	0	Subcode sync signal output terminal.	
. 8	SUBQ	0	Subcode Q data output terminal.	
9	SBOK	0	Subcode Q data CRC check result output terminal. "H" when check result is OK.	
10	XI	1	X'tal resonator connection terminals.	
11	XO	0	X'tal resonator connection terminals.	
12	VDDD	-	Digital power supply terminal (+5V),	
13	GNDD	-	Digital grounding terminal.	
14	BUS0	1/0	Command and data send / receive I/O terminals.	Schmitt inputs.
17	BUS3	1/0	Command and data send / receive I/O terminals.	Schmitt inputs.
18	CCE	I	Command and data send / receive Chip Enable signal input terminal.	
			"L" for making the bus line active.	

CIRCUIT DESCRIPTION

Pin No.	Symbol	1/0				1	Function			Remark
19	BUCK	1	Command and data send / receive clock input terminal.							
20	4MCK	0	4M clock output terminal (4.2336MHz).							
21	RST	1								With pull-up resistor
22	CCNT	1	Subcode Q data control bit update inhibit signal input terminal.						Emphasis, copy and	
			"H" for inhibi							channel information
23	SUBD	0	Subcode P -	0	erminal.					
24	CLCK	1		- W data read		nout te	rminal			
25	LOCK	0						c nattern in	EFM signal of over	run
	200		4	ta has not be				o pattorr iir	Er ivi digital di dvori	
26	TEST1			rmally "H" or		0000 10	7 171110.			With pull-up resistor.
27	DFCT	0				inal Ve	se when de	tect is detec	cted, HiZ in normal	
28, 29	TEL2, 1	0	Tracking gair		***************************************					0030
30	TGUL	0					· · · · · · · · · · · · · · · · · · ·		loop phase compen	62
30	IGOL						-	-	n normal case.	54-
31	TGUH2								loop phase compen	00
31	IGUHZ							-		
22	TCUI	0		_		_			tected, VREF in norm	
32 TGU1				case. TGUH1 is used in normal-speed playback, and TGUH2 is used in double-speed				ea		
00	TVIC	_	playback.				1 1. #1.#1. f.	12.12		
33	TKIC	0					ninal, "H" for	kicking tow	ard the outer edge.	
				ng toward the			1: 6 1	01111		
34	FMON			ch output ten				ervo ON / (DFF.	
	=	0	Feed servo		-		10N			
35	FMON		ON	Hiz			REF			
			OFF	VRE			liZ			
36	FMFB	0	Feed motor				_			3-level output.
				toward the o		e. "L" f	or feed tow	ard the inne	r edge.	
37	TEST		Test pin. No							With pull-up resistor.
38	DMON	0		ch output ter				motor driv	er gain.	
				CLV servo Al						
			Command				Operation			3-level output.
39	DMFC	0	DMFK	Н		Moto	r acceleration	on		· -
			DMSV	PW		CT/	V servo ON			
			DMBK	DMBK L Motor deceleration						
			DMOFF	VRE	F	CLV	/ servo OFF			
40	DMPC	0	Disc motor	CLV servo A	PC signa	al outpu	it terminal.			3-level output.
41	2VREF		Double refer	ence voltage	input te	erminal	(VREF x 2).			
			Servo mode	select signa	output	termina	al.			
			SEL LD O	N / OFF Fo	ocusing s	servo (Operation m	ode		
42	SEL	0	L (OFF	OFF		LD OFF			3-level output.
			HiZ	ON	OFF	F	ocusing se	arch		
			Н	ON	ON		Normal pla	зу		
			Focus actuar	tor drive sign	nal output	t termir			de.	
			Command	FCSI or			Opera			
43	FCSI					3-level output.				
		"								
-10			FOSET	L	1	1 4	ens aets cic	ser to disc	1	

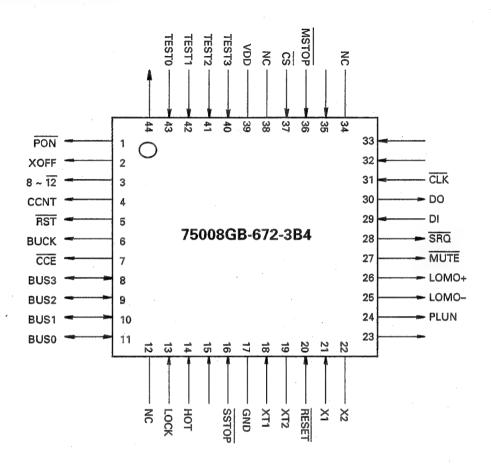
CIRCUIT DESCRIPTION

Pin No.	Symbol	1/0	Functio	n	Remark
	Focus actuator drive signal output terminal for focus gain adjustment mode.				
			Other HiZ Other oper	ation than focus search.	
			Command FKIC output	Operation	
44	FKIC	0	FGASR H	Lens gets apart from disc.	3-level output.
			FGASS L	Lens gets closer to disc.	•
			Other HiZ Other	operation than focus gain adjustment	
45, 46	FEL2, 1	0	Analog switch output terminals for focus ga	in adjustment.	
47	FEI	1	Focusing error signal input terminal.		Analog input.
48	TESH	1	Analog switch input terminal for tracking erro	or signal sample & hold operation.	
49	TEOF	0	Analog switch output terminal for tracking se	ervo operation ON / OFF.	
			VREF when tracking servo is OFF.		
50	SBAD	- 1	Sub-beam addition signal input terminal.		Analog input.
51	RFRP	1	RF ripple signal input terminal.		
52	VREF	1	Reference voltage input terminal (+2.2V).		
53	RFI	1	RF signal input terminal.		Analog input.
54	GNDA	-	Analog ground terminal.		
55	DTSC	0	EFM signal inverted output terminal for data	slice control.	
56	EFMO	. 0	EFM signal monitoring output terminal.		Binary data.
57	DTSC1	0	EFM signal output terminal for data slice cor	ntrol.	
58	VDDA	_	Analog power supply terminal (+5V).		
59	PDCNT		PDO output control terminal. "L" for forcing f	PDO output to HiZ.	
60	PDO	0	EFM / PLCK phase error signal output termin		3-level output.
			TMAX signal output terminal. HiZ when sys		
			TMAX cycle TMAX		
61	TMAX	0	Longer than specified cycle		3-level output.
			Shorter than specified cycle H (2)	/REF)	
			Equal to specified cycle H		
62	LPFN	1	LPF amp inverted input terminal for PLL.		
63	LPFO	0	LPF amp output terminal for PLL.		
64	VCOF.	1	VCO filter terminal.		
65	VCOX	1	External VCO clock input terminal.		
66	PLCK	0	Playback data read clock output terminal.		
67	MOD0				
68	MOD1	1	Internal operation mode setting input termin	als.	
69	MOD2	1			
70	WDCK	0	Word clock output terminal. Normally 88.2kl	⊣z.	
71	CHCK	0	Channel clock output terminal. Normally 44.		
72	ВСК	0	Bit clock output terminal. Normally 1.4112N		
73	AOUT	0	Audio data output terminal.		
74	CKSE	I	Internal clock select terminal.		
75	DOUT	0	Digital output terminal.		
76	TEST2	1	Test pin. Normally "H" or Open.		With pull-up resistor.
77	HS	0	High-speed monitoring output terminal. "L" f	or double-speed operation.	
78	EMPH	0	Emphasis ON / OFF indication signal output		
79	TEST3	T	Test pin. Normally "H" or Open.		With pull-up resistor.
	MCK	0	Master clock output terminal.		

CIRCUIT DESCRIPTION

4. Mechanism Microprocessor: 75008GB-672-3B4 (X32-2210) IC6

4-1. Terminal connection diagram



4-2. Terminal descriptions

Pin name	Also used as	1/0	Port name	Description
	used as			
72				
	KR6	0	PON	+5V POWER CONTROL. For TC9236F, etc. "L" for ON.
71	KR5	0	XOFF	SERVO CLOCK OFF (16MHz), "H" for OFF.
70	KR4	0	8-12	DISC SIZE SW. "H" for 8cm
63	KR3	0	CCNT	TC9236F SUB-CODE UPDATE INHIBIT OUT. "H" for inhibit.
62	KR2	0	RST	TC9236F RESET. "L" for reset.
61	KR1	0	BUCK	TC9236FCOMMAND / DATA COMMUNICATION CLOCK.
60	KR0	0	CCE	TC9236F CHIP ENABLE. "L" for Active.
53~50		1/0	BUS3~0	TC9236F COMMAND / DATA COMMUNICATION BUS.
IC				
43			LOCK	EFM LOCK SIGNAL FROM TC9236F, "H" for lock.
42		1	HOT	TEMPERATURE RISE DETECT. "H" for temperature rise.
41		1		Not used. Connected to GND.
40		1	SSTOP	SLED LIMIT SW. "L" for inner limit.
'ss			GND	Connected to GND.
T1		ı	XT1	SUB-CLOCK INPUT. Not used, connected to GND.
T2		0	XT2	OPEN _
7 6 6 6 6 5 IC 4 4 4 S T	0 3 2 1 0 3~50 2 3 2 1 0 0 8 1	0 KR4 3 KR3 2 KR2 1 KR1 0 KR0 3~50 2 3 2 1 0 SS	0 KR4 O 3 KR3 O 2 KR2 O 1 KR1 O 0 KR0 O 3~50 I/O 5 3 I 2 I 1 I 0 I 8	0 KR4 0 8-12 3 KR3 0 CCNT 2 KR2 0 RST 1 KR1 0 BUCK 0 KR0 0 CCE 3~50 I/O BUS3~0 3 I LOCK 2 I HOT 1 I SSTOP S GND 1 XT1

CIRCUIT DESCRIPTION

Pin	Pin	Also	1/0	Port name	Description	
No.	name	used as				
20	RESET		1	RESET	μ-COM RESET INPUT. "L" for reset.	
21	X1		1	X1	MAIN CLOCK. Connect a 4.19MHz oscillator.	
22	X2		0	X2		
23	P33		0	SEARCH	Search status output. "L" during search.	
24	P32		0			
25	P31		0	LOMO-	CD MECHANISM LOAD MOTOR	
26	P30		0	LOMO+	CD MECHANISM LOAD MOTOR +.	
27	P81		0	MUTE	MUTE OUT. "L" → MUTE ON.	
28	P80		0	SRQ	COMMUNICATION REQUEST TO SYSTEM CONTROLLER, "L"→ Requesting.	
29	P03	SI /SB1	I	Di	SERIAL DATA INPUT FROM SYSTEM CONTROLLER.	
30	P02	SO / SB0	0	DO	SERIAL DATA OUTPUT TO SYSTEM CONTROLLER.	
31	P01	SCK	1	CLK	SERIAL COMMUNICATION CLOCK FROM SYSTEM CONTROLLER.	
32	P00	INT4	1		Not used. Connected to GND.	
33	P13	TIO	1		Not used. Connected to GND.	
34	NC					
35	P12	INT2			Not used. Connected to GND.	
36	P11	INT1	L	MSOP	MECHANISM μ-COM STOP. "L" → Stop and oscillation end.	
37	P10	INT0		CS	COMMUNICATION REQUEST FROM SYSTEM CONTROLLER. "L" → requesting.	
38	NC					
39	VDD			VDD	POWER +5V	
40	P23		1	TEST3	TEST INPUT TERMINAL 3. "H"─➤Test mode.	
41	P22		1	TEST2	TEST INPUT TERMINAL 2. "H" → Test mode.	
42	P21		ı	TEST1	TEST INPUT TERMINAL 1. "H" → Test mode.	
43	P20	PTO0	1	TEST0	TEST INPUT TERMINAL 0. "H"→ Test mode.	
44	P73	KR7	0		OPEN	

CIRCUIT DESCRIPTION

4-3. Mechanism microprocessor test mode

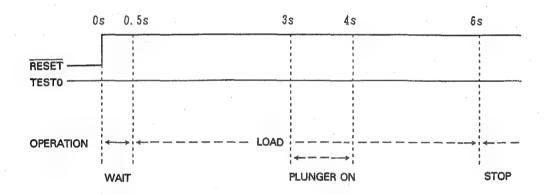
This test modes are provided to allow the mechanism microcomputer checking the servo system without the help of the system controller, for example when the mechanism deck is manufactured, etc. It also allows the mechanism microcomputer alone to load of eject a disc.

Setting methods and operations

Regardless of the system controller, the test mode can be set by reading the test terminals at the time of resetting. The three kinds of modes as described below can be set according to the statuses of the four test terminals. In any test mode, it is required that the servo and mechanism power supplies have already been turned on before resetting.

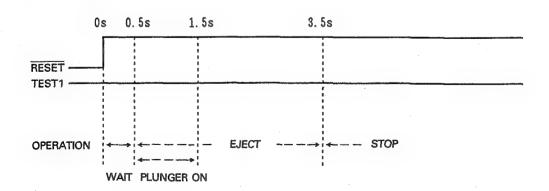
(1) Self loading

Loading starts when the TEST0 terminal is "H" at the time of resetting. However, as the mechanism microcomputer does not check the sensor, the loading always starts with the same timing as shown below. Therefore, if the chucking is correct or not can be checked visually or by monitoring DOWN SW.



(2) Self-ejection

Ejection starts when the TEST1 terminal is set to "H" at the time of resetting. Similarly to the case of self-loading, the timing is constant as shown below.



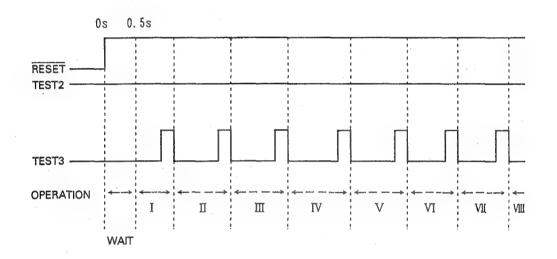
CIRCUIT DESCRIPTION

(3) Servo testing

The servo check mode can be entered when the TEST2 terminal is set to "H" at the time of resetting. Under this condition, applying a "H" pulse to the TEST3 terminal starts sequential operations of the mechanism and servo system, allowing checking of the operations. If both the TEST2 and TEST3 terminals are set to "H" at the time of resetting, the operations shown below occur automatically, and the last track will be played.

Due to the chattering cutting, only pulses in the range from 100ms to 1sec. are accepted as the input to the TEST3 terminal. The servo-related settings are constant with 12cm discs.

Note: The test mode can be canceled by resetting or entering the stop mode. Communications with the system controller is not performed in the test mode. In case the test terminals should go "H" together, the priority is set in the order of TEST0, TEST1 then TEST2.



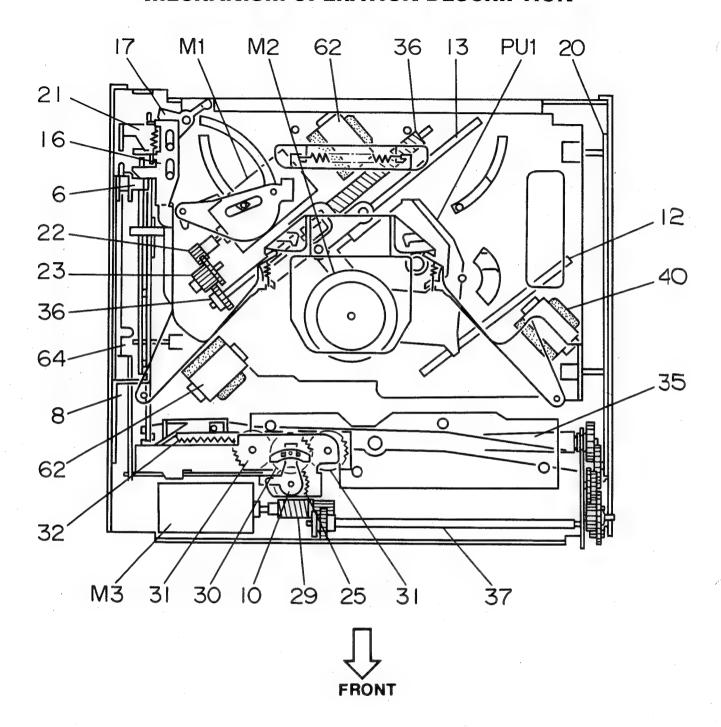
- I. Stop. No operation until a pulse is input.
- II. Feed motor set to the origin point.
- III. Laser diode ON.
- IV. Focus servo ON.

- V. Disc motor kick, CLV ON.
- VI. Tracking and feed servo ON.
- VII. First track play.
- VIII. Last track search and play.

Because of the chattering cutting, only pulses with durations of 100ms to 1sec. are accepted in TEST3. The servo-related setting are constant with 12cm disc.

Note: The test mode can be released by resetting the microcomputer or entering the stop mode. Communicatons with the system controller are not performed in the test modes. If more than one test terminal is "H" simultaneously, the test mode is selected in order of priority from TEST0 to TEST1 and TEST2.

MECHANISM OPERATION DESCRIPTION



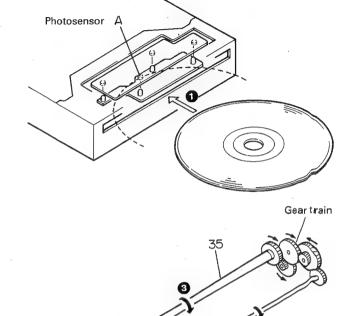
Note : Figures in the bracket () in the operation description or accompanied with the part name in the diagram show the reference numbers in the Exploded View.

MECHANISM OPERATION DESCRIPTION

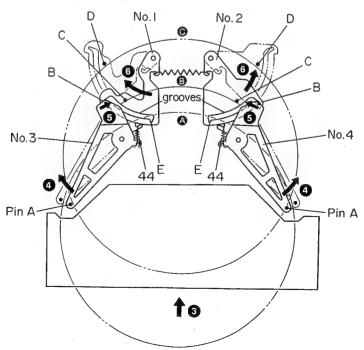
Loading

- 1. A CD is inserted (1).
- 2. Photosensor A detects the disc insertion.
- 3. The loading motor (M3) starts rotation according to the microcomputer instruction.

- 4. The rotation is transmitted through the worm gaer (29), drive shaft (37) and gear train, up to the loading roller (35). (2)
- The CD is pulled by the friction of the rubber roller(3).



- 6. When the CD is advanced to position pins "A" installed on levers 3 and 4 are widened by the disc on levers 1 and 2, levers 1 and 2.
 - periphery.
 As lever 3 rotates clockwise and lever 4 rotates counterclockwise, (4) lock claw "B" is disengaged from the lock consisting of the lock grooves on levers 1 and 2 (5).
- 7. When the CD contacts positioning pins "C" installed on levers 1 and 2, levers 1 and 2 are pushed by the CD, causing lever 1 to rotate clockwise and lever 2 to rotate counterclockwise. (The position of the CD at this time is shown as position (3).)

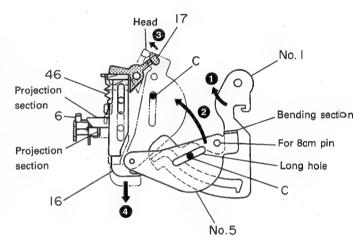


MECHANISM OPERATION DESCRIPTION

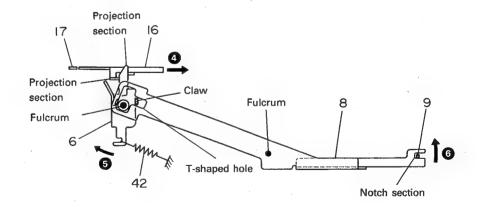
- 8. As CD advances more, levers 1 and 2 rotate more, the positioning pin attains position "D", and the CD comes to position which is above the turntable.
- Presently, levers 1 lever 2 are located in the position with which lock position "E" on the opposite sides of their lock grooves are engaged with lock claws "B" of levers 3 and 4. As the CD has passed pins "A" of levers 3 and 4, levers 3 and 4 are re-
- turned to their original positions by spring (44). As a result, levers 1 and 2 are locked by the lock claws of levers 3 and 4. This timing is the completion of positioning of CD.
- 10. When the disc is a 8cm disc, levers 3 and 4 do not operate, so the levers 1 and 2 are not unlocked and the CD is positioned at the position of pins "C".

2. Chucking

- When lever 1 rotates clockwise (1) in the loading operation described above, lever 5, which is connected via positioning pin "C" and long hole-shaped guide groove, is rotated counterclockwise by the action of positioning pin "C" (2).
- 2. The "bending section" on the tip of lever 5 pushes the "head" of lever 17, which starts to rotate counterclockwise (3).
- 3. The "projection section" on the other side of lever 17 is in contact with the slide lever 16. When lever 17 rotates counterclockwise, the slide lever 16 is slid in the lower direction of the figure (4).



- 4. The "projection section" of the slide lever 16 is designed to come in contact with the projection section of lever 6, which is rotated clockwise when the slide lever moves (5).
- 5. The claw installed on lever 6 is engaged with the "T-shaped hole" on lever 8, which is rotated counter-clokwise when lever 6 rotates clockwise (6).

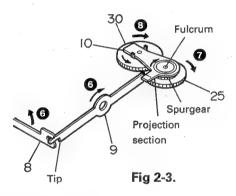


MECHANISM OPERATION DESCRIPTION

6. In Fig. 2-3, the worm wheel (25) held on the same shaft as the friction arm (10) is rotated clockwise by the rotation of the worm gear described above (12).

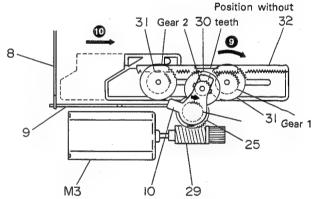
The spur gear integrated with the worm wheel (25) is meshed with the planetary gear (30), and rotates counterclockwise. A leaf spring, which is not shown in the figure, is inserted between the planetary gear (30) and the friction arm (10) in order to generate a friction force between them. This friction force ensures that the friction arm (10) rotates always clockwise (3).

- 7. The "notch section" on the tip of lever 8 is enga ged with the tip of lever 9.
- 8. The "tip section" on the other end of lever 9 is contacted by the "projection section" of the friction arm (10) described before. This contact prevents the clockwise rotation of the friction arm.
- 9. As a result of the sequence of operations starting with the movement of lever 1 described before, the "notch section" of lever 8 rises, lever 9 rotates clockwise (6), and the contact of the projection section of the friction arm is separated. This frees the friction arm (10) and it starts clockwise rotation (8).



10. When the friction arm (10) rotates clockwise, the planetary pinion of the planetary gear (30) is meshed with gear 1, which starts clockwise rotation (3). As gear 1' integrated with gear 1 is meshed with the rack gear (32), the rack gear starts to move toward the right (10).

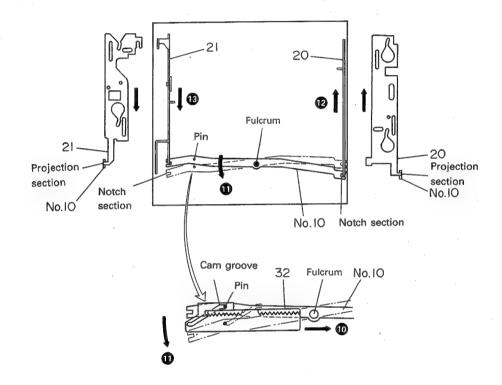
When the rack gear moves further toward the right, gear 1' and the rack gear are disengaged at the position without teeth, and the rack gear stops to move.



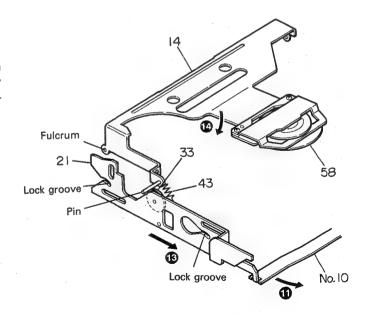
MECHANISM OPERATION DESCRIPTION

- 11. The cam groove provided on the rack gear (32) activates the pin of lever 10 supported by a shaft on the chassis, and lever 10 rotates counterclockwise (11).
- 12. Into the notch sections on both ends of lever 10, the projection sections of cam 20 and cam 21 are engaged.

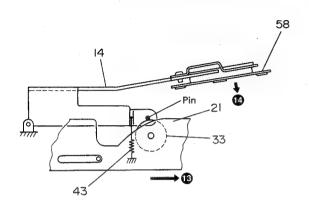
Cams 20 and 21 are held by the chassis so that they can slide freely. When lever 10 rotates counterclockwise, cam 20 moves upward (12) in the figure and cam 21 moves downward in the figure (13).

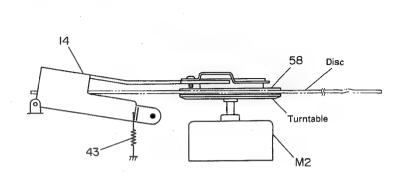


13. A roller (33) is supported by a shaft above cam 21. The roller supports the pin on the clamp lever (14) so the clamper (58) is in the up position. When cam 21 moves, the roller is separated from the pin, and the clamp lever is moved downward by the force of the spring (43) to fix the CD on the turntable (12).

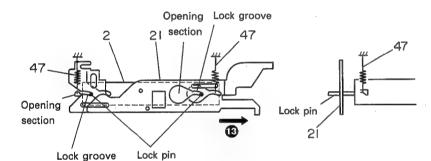


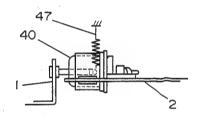
MECHANISM OPERATION DESCRIPTION



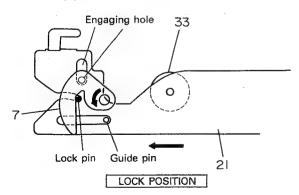


- 14. Cam 21 has a lock groove, in which the lock pin of the pickup chassis (2) is engaged. The pickup chassis is fixed. When cam 21 moves, the lock pin is relatively moved to the opening section. This frees the pickup chassis, which is held in the floating status by the suspension spring (47) and damper (40).
- 15. Cam 20 also has a lock groove and opening similarly to cam 21. It is subject to the lock and unlock operations between the lock pin on the pickup chassis.

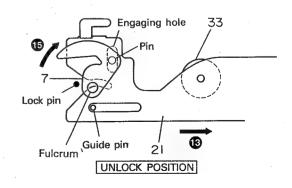




- 16. The lock lever (7) is supported by a shaft on the chassis, and the pin (actually a projection with burrs) on the lock lever is engaged into the engaging hole on cam 21. The cam is held by the guide pin so that it can move freely toward the front or rear of the chassis.
- 17. Before loading of the CD, cam 21 is the lock position shown in the figure. In this position, the lock section of the lock lever (7) prevents, or locks, the horizontal movement of the lock pin of the pickup chassis (2).



- When a CD is loaded as described before, cam 21 moves toward the right in the figure and the lock lever (7) starts clockwise rotation (16) This causes the lock section to move upward and the lock pin of the pickup chassis is freed. The horizontal movement of the pickup chassis is locked or unlocked based on the above.
- 18. Although not shown in the figure, a similar lock lever is also used with cam 20 to lock or unlock the front right side of the pickup chassis.



MECHANISM OPERATION DESCRIPTION

19. Cam 21 has a cam section which is in contact with drive pin 1 of the roller lever (18).

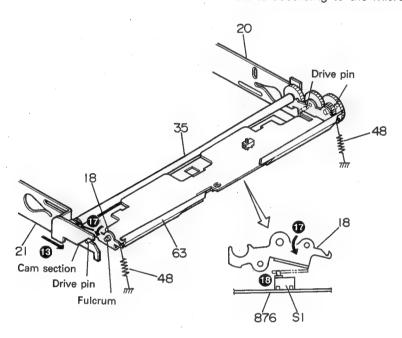
When a CD is loaded as described before, cam 21 moves toward the right in the figure, its cam section pushes the drive pin, and the roller lever (18) starts counterclockwise rotation. (The same operation occurs also with cam 20.) (17)

As a result, the loading roller (35) goes downward, the contact between the CD and the roller is separated, and the CD transport is stopped.

20. A switch (S1) is installed below the roller lever (18, and turned ON when the roller lever goes down ward (18).

The microcomputer identifies the completion of chucking when this switch is turned ON. However, the motor rotation is continued for more about 0.5 second to allow a margin until the actions in other mechanisms terminate completely. After this, the motor (M3) rotation stops based on the judgment of the completion of chucking.

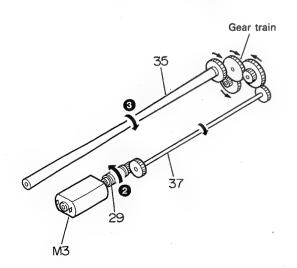
21. After the completion of chucking, the playback starts according to the microcomputer instruction.

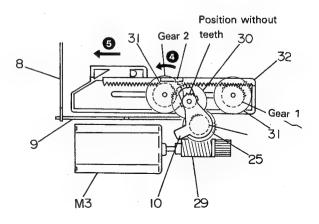


3. Ejection

1. When the eject button is pressed, the loading motor (M3) starts inverse rotation (2).

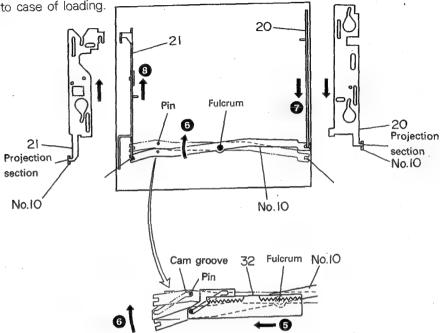
2. The friction arm (10) rotates counterclokwise, and the rack gear (32) moves toward the left (4) (5).



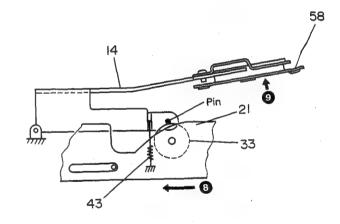


MECHANISM OPERATION DESCRIPTION

3. Cam 20 and 21 lock the pickup chassis by acting in the opposite ways to case of loading.



- 4. The lift roller (33) pushes the clamp lever (14) upward, thereby moving the clamper (58) upward
- The loading roller (35) moves upward and the door moves downward. The disc is ejected by pressure.



4. Playback

- 1. When the disc is chucked and the DOWN switch (S1) is turned ON, the microcomputer checks the limit switch (*1). If it is OFF, the sled motor (*2) is rotated to feed the pickup toward the inner periphery and turn the switch ON.
- When the limit switch is turned ON, the pickup is activated, the focusing servo then the tracking servo are applied, the spindle motor (M2) is rotated, and playback is started.
- 3. When the stop button is pressed, all servoes are

- turned OFF while the pickup position is not changed.
- 4. When the eject button is pressed, the ejection operation is performed a described before. At the same time, the pickup is fed toward the inner periphery and stopped when the limit switch is turned ON.
 - *1 Switch which is turned ON when the pickup is on the inner periphery position.
 - *2 Motor which moves the pickup toward the inner

MECHANISM OPERATION DESCRIPTION

5. Mechanism operation timing

5-1. Control terminals

Out put terminal

- ① Motor (+) terminal
- Motor (-) terminal

Input terminals

- 1) Photosensor (A) terminal
- 2 Photosensor (B, D) terminal
- ③ Photosensor (C) terminal
- *2 5 DOWN switch
- *1 Chattering shall be 20 ms.
- *2 Chattering shall be 30 ms.

5-2 Loading operations

Loading start conditions

- · Loading start from the status without disc : Loading starts when one of photosensors A, (B, D) and C is turned ON.
- Loading start from the status after completion of ejection of 12cm disc [when only photosensors A and (B, D) are ON]: Loading starts when photosensor C is turned ON.

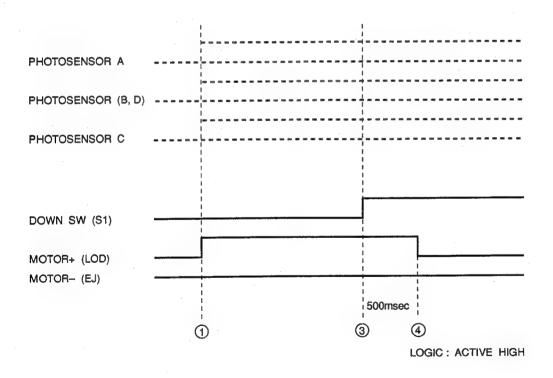
• Loading starts from the status after completion of ejection of 8cm disc [when only photosensor A is ON]: Loading starts when photosensor (B, D) is turned ON.

Loading control methods

- ① When one of the loading start conditions is met, the motor is driven toward the loading direction.
- 3 When the DOWN switch is turned ON, the motor is driven for 500ms, after which it is stopped.
- 4 Photosensors A and (B. D) check whether the disc is 8cm or 12cm.

Loading protection operation

- In case loading does not complete in 8 seconds after the start, the operation transits to ejection. If the ejection does not complete in 8 seconds again, the operation is stopped immediately.
- If all photosensors are OFF for 1 seconds in the period between the start and completion of loading, the loading is stopped based on the judgment that the disc has been removed.



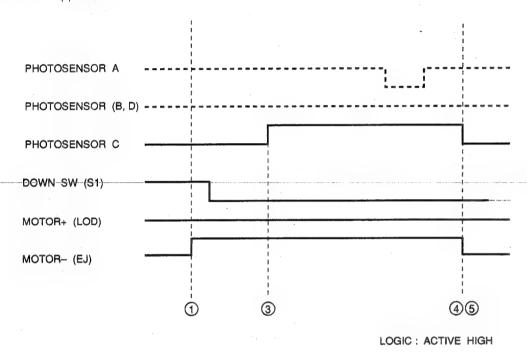
KDC-67R/68R KDC-67R/68R

MECHANISM OPERATION DESCRIPTION

5-3. Ejection operation

Ejection control methods

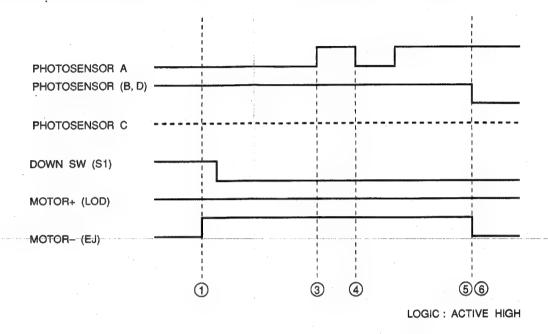
- [1] Ejection control from the status in which 12cm disc
- 1) The motor is driven in the ejection direction.
- 3 Photosensor C is turned ON.
- A Photosensor C is turned OFF.
- (5) The motor is stopped.



MECHANISM OPERATION DESCRIPTION

- [2] Ejection control from the status in which 8cm disc is
- 1) The motor is driven in the ejection direction.
- 3 Photosensor A is turned ON.

- 4 Photosensor A is turned OFF.
- (B, D) is turned OFF.
- 6 The motor is stopped.



KDC-67R/68R KDC-67R/68R

MECHANISM OPERATION DESCRIPTION

- [3] Ejection control from the status in disc is located in the middle
- In case the presence of disc can be identified with a photosensor: The loading completion status is set temporarily to identify the disc size, then ejection is restarted.
- In case the photosensors, END switch and DOWN switch are all OFF:
- (1) The motor is driven in the ejection direction for 500ms.
- (2) When a photosensor reacts, the loading completion status is set temporarily to identify the disc size. then ejection is restarted.

Ejection protect operation

- In case ejection does not complete in 8 seconds after the start, the operation transits to loading. If loading does not complete in 8 seconds again, the operation is stopped immediately.
- If all photosensors are OFF for 1seconds in the period between the start and completion of ejection, the ejection is stopped based on the judgment that the disc has been removed.
- If the DOWN switch is ON while all photosensors are OFF, ejection is performed. (Because loading is possible even when disc is absent, for example in test mode.)

5-4. Momentary OFF during loading or ejection.

- Momentary OFF during loading: Loading is stopped temporarily. When the momentary OFF is released. loading is restarted from the same position.
- Momentary OFF during ejection : Ejection is stopped temporarily. When the momentary OFF is released, the loading completion status is set, the disc size is identified, and ejection is started again.

5-5. Acc ON/OFF during loading of ejection.

- Acc ON/OFF during loading: Loading is countinued until completion. However, the protect timer is activated, and loading is stopped if the timer overflows.
- Acc ON/OFF during ejection : Ejection is coutinued until completion. However, the protect timer is activated, and ejection is stopped if the timer overflows.

SUPPLEMENT RELATED TO LOADING/EJECTION OF DXM-200 (CD-MECHANISM)

1, 8/12cm disc size identification method The disc size is identified using photosensors A and (B, D) in the chucking completion status.

A OFF, B/D OFF = 12cm

A OFF, B/D ON = 8cm

A OFF, B/D ON = 12cm (abnormal)

A ON, B/D ON = 8cm (abnormal)

2. Ejection in chucking status without disc. If ejection is started while the DOWN switch is ON, the motor keeps on running for more 700 milliseconds even if all photosensors are OFF, then the one-second timer for checking if all photosensors are OFF is started. Therefore, if ejection is started without disc, the motor should rotate for two seconds, making it possible to set the mechanism to the complete ejection status.

ADJUSTMENT

1. Tracking offset adjustment

- 1. Connect a test jumper wire between the test point (TEST2) and (+5V).
- 2. Connect a test jumper wire between the test point (TOFF) and (Vref).
- 3. Connect an oscilloscope between the test point (TE) and (Vref).
- 4. Put the set into play mode by loading the disc.
- 5. Adjust VR2 so that the oscilloscope reading is symmetrical in relation to 0V.
- 6. After adjusting, reset 1 and 2 as original.

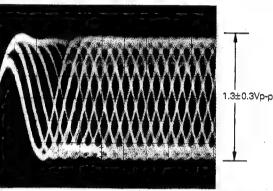


2. Focus offset adjustment

- 1. Connect an oscilloscope to the test point (RF).
- 2. Put the set into play mode by loading the disc.
- 3. Adjust VR1 so that the oscilloscope waveform eve pattern is good.

A good eye pattern means that the diamond shale (0) in the center of the oscilloscope can be clearly distinguished.

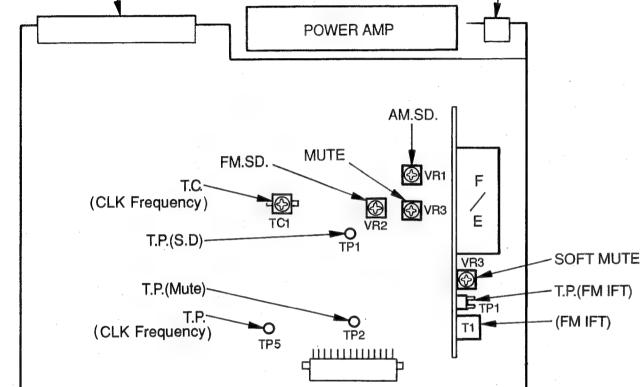
Volt/Div : 200mV Timer/Div: 0.5usec.

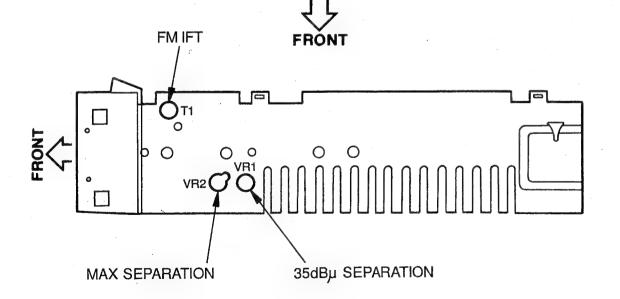


KDC-67R/68R KDC-67R/68R

ADJUSTMENT

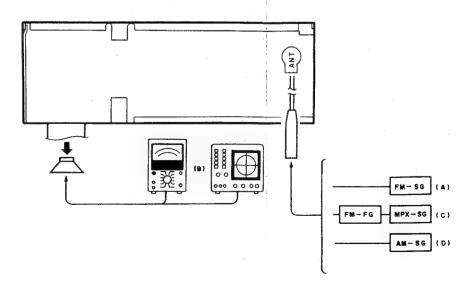
T.P.C.CN ANT CN POWER AMP

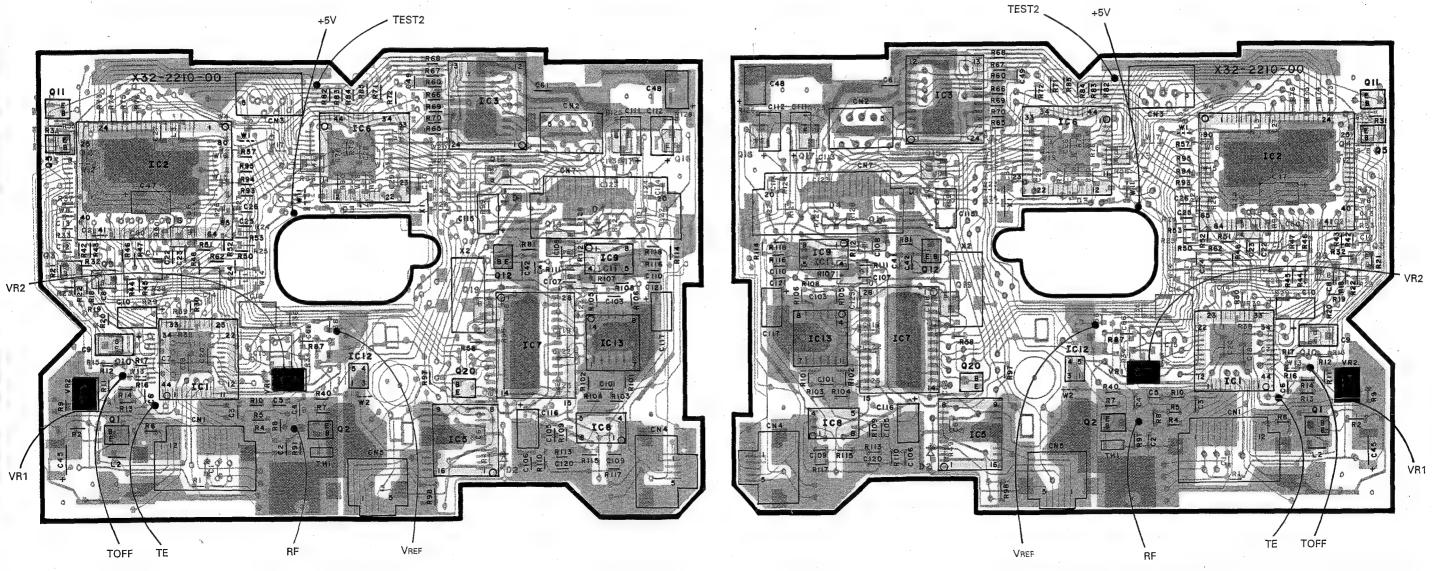




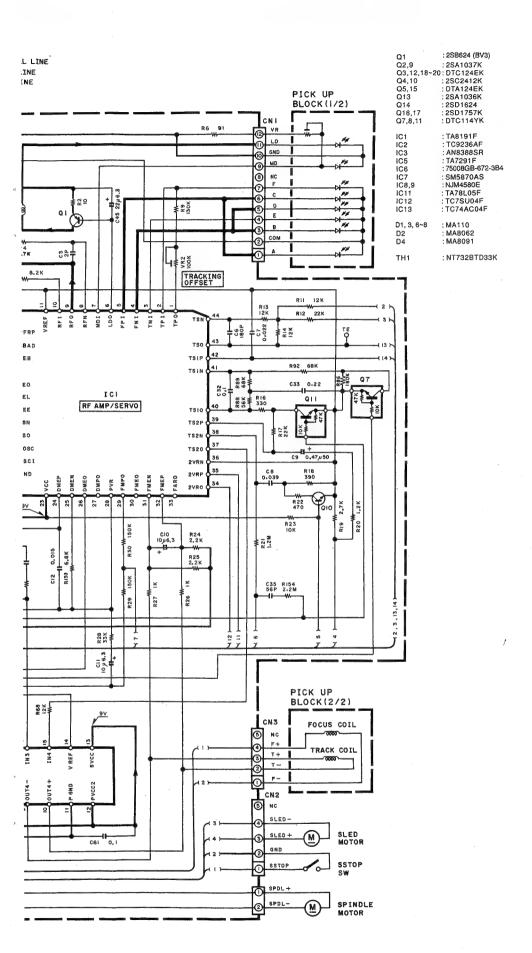
ADJUSTMENT

		INPUT	OUTPUT	TUNER (RECEIVER)	ALIGMENT		Τ
No.	ITEM	SETTINGS	SETTINGS	SETTING	POINTS	ALIGN FOR	FIG
FM	SECTION						
-		(A)	Connect the				
		98.1MHz	DC voltmeter	FM	T1		
1	DISCRIMINATOR	0dev	between pins	98.1Mkz	(X86)	ov	(a)
		60dBμ(ANT input)	of TP1 (X86)				
		(C)		,			
2	SEPA-	98.1MHz		FM	VR2	Adjust it so that	
	RATION	1kHz, ±67.5kHz dev	(B)	98.1MHz	(X86)	the crosstalk from L to R	
		Pilot: ±7.5kHz deV				and R to L become	1
		Selector : L or R				minimum.	
		60dBμ(ANT input)		:			
		(C) /		1			
		98.1MHz	*	*			
3	ANRC	1kHz, ±67.5kHz dev		FM	VR1	Separation	
		Pilot : ±7.5kHz deV	(B)	98.1MHz	(X86)	10dB	
		Selector : L or R					
	<u>.</u>	35dBμ(ANT input)		:			
		(A)	Connect the				
.4	MUTE	98.1MHz	DC voltmeter to	FM	VR3	Low → Hight (Voltage)	
		1kHz, ±75kHz dev	TP2	98.1MHz	(X25)	(MUTE → ON)	(b)
		5dBμ(ANT input)	(X25)	,			
		(A)					1
	SEEK	98.1kHz		FM	VR3		
5	MUTE	1kHz, ±75kHz dev	_	98.1kHz	(X25)	Seek stop	
	LEVEL	20dBμ → No input		SEEK : ON			
		(A)				Output Noise level	
	SOFT	98.1kHz		FM	VR3	-25dBµ	
6	MUTE	1kHz, ±75kHz dev	(B)	98.1kMz	(X86)	(When not add any signal	
	LEVEL	60dB μ → No input				to ANT terminal)	
AM	SECTION	·					
		(D)					T
	SEEK	1000kHz		AM	VR1		
(1)	STOP	400Hz, 30% mod		1000kHz	(X25)	Seek stop	
	LEVEL	35dBμ (ANT input)			,	•	
	1	*					





Refer to the schematic diagram for the values of resistors and capacitors.



AN8388SR



75112GF-732-3BE

2SD1624

LM7001

M5236ML

TA78L05F

TC9188F

SM5870AS



AN7174K

2SB1187F8 2SD1266BD 2SB1277



DTA124EK 2SC2412K DTC114EK 2SD1757K DTC124EK 2SA1036K DTC144EK 2SC2413K 2SA1037K



2SB1050



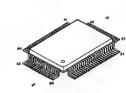
M5201FP NJM4565MD NJM4580E



2SK669



TC9236AF

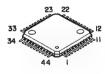


TA7291F



TC74AC04AF TC4066BF

TA8191F 75008GB-672-3B4

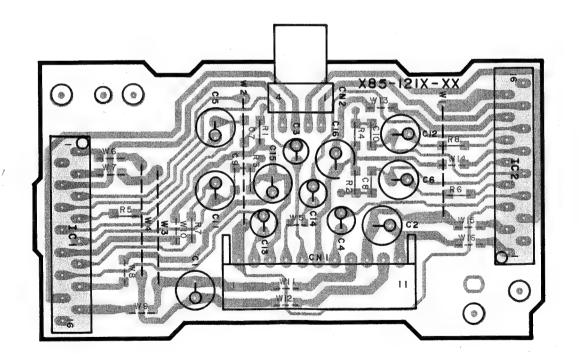


 DC voltages are as measured with a high impedance voltmeter. Values may vary slightly due to variations between individual instruments or/and units.

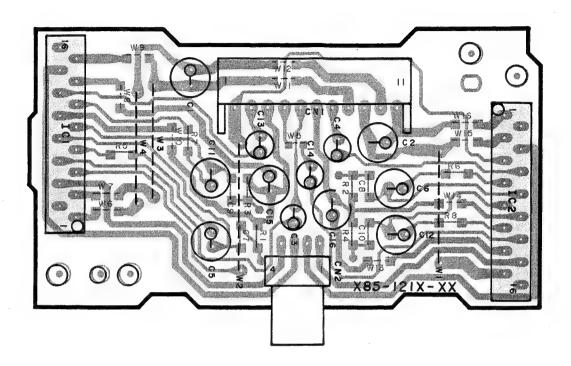
CAUTION: For continued safety, replace safety critical components only with manufacturer's recommended parts (refer to parts list). △ Indicates safety critical components. To reduce the risk of electric shock, leakage-current or resistance measurements shall be carried out (exposed parts are acceptably insulated from the supply circuit) before the appliance is returned to the customer.

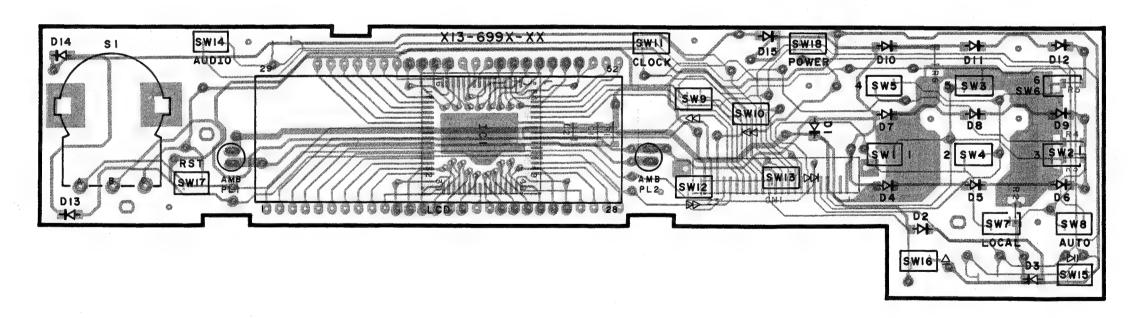
KENWOOD

| SWI | SWI



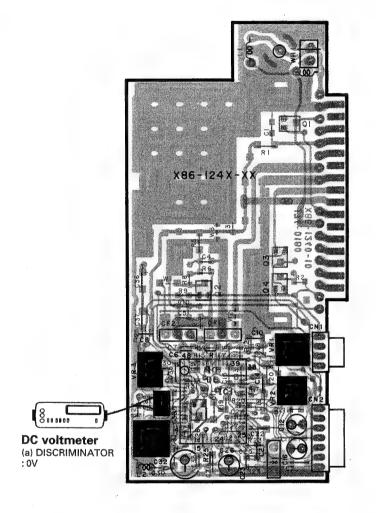
Refer to the schematic diagram for the values of resistors and capacitors.

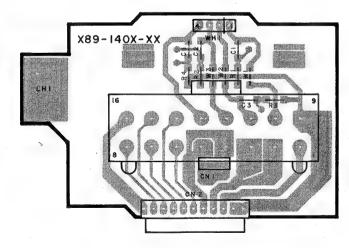




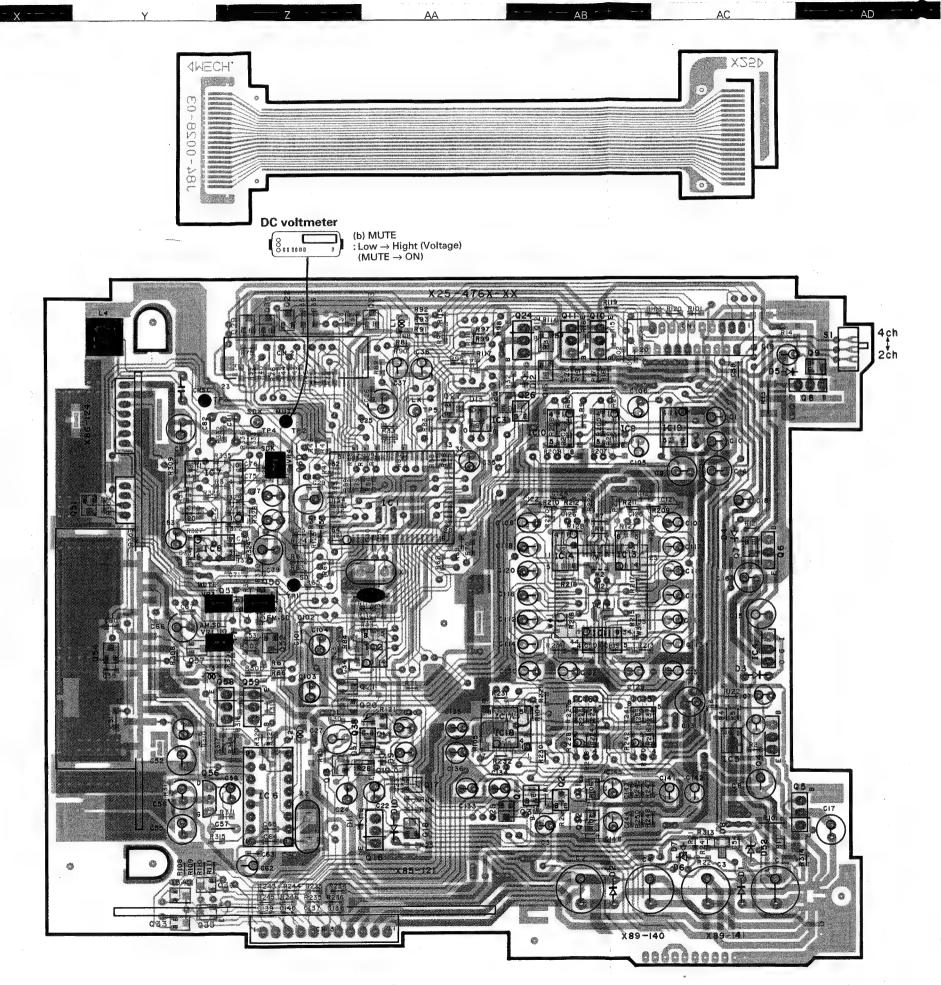
Refer to the schematic diagram for the values of resistors and capacitors.

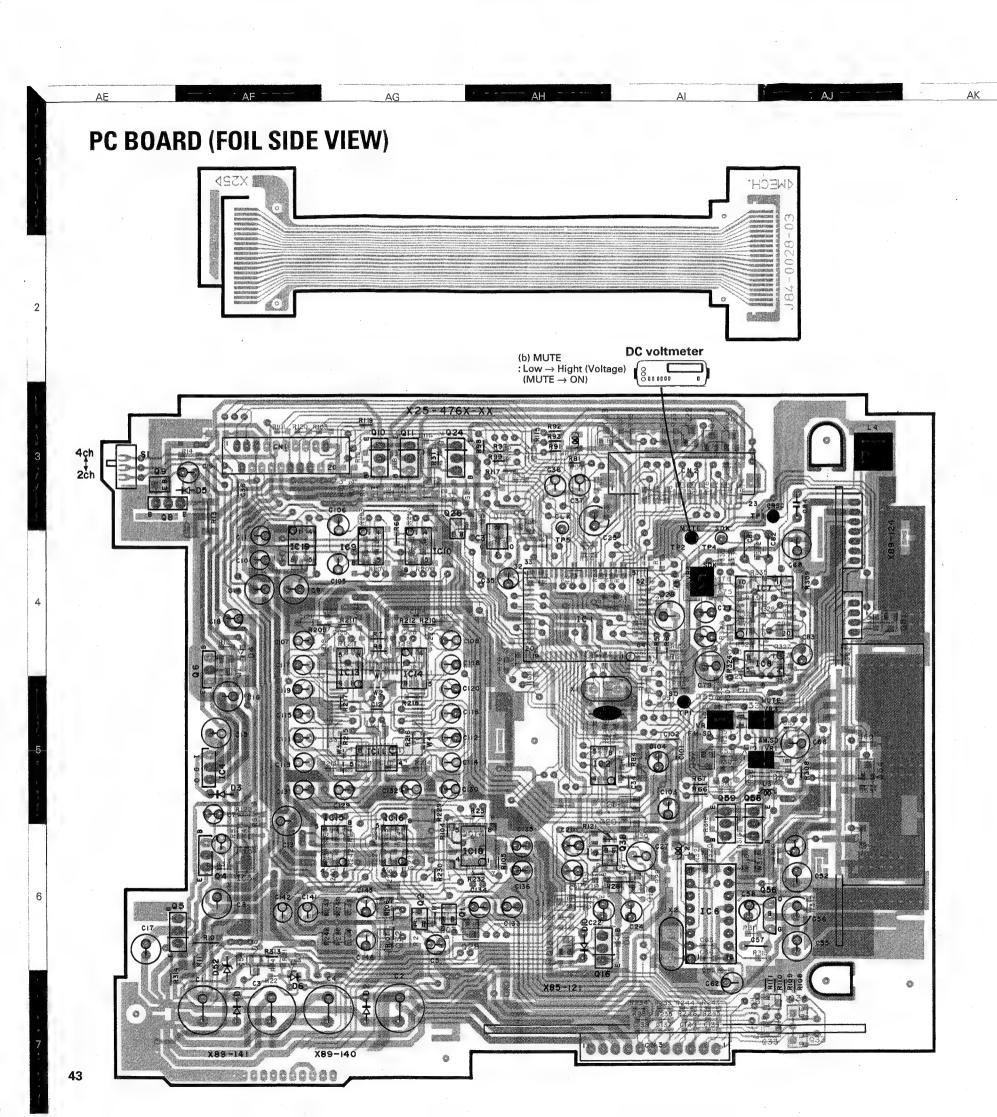
PC BOARD (COMPONENT SIDE VIEW)

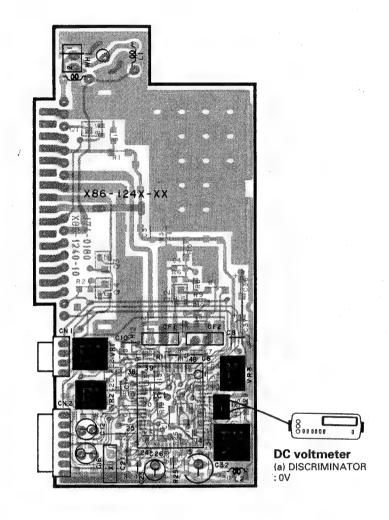


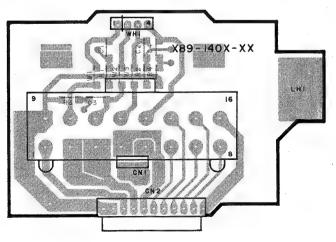


Refer to the schematic diagram for the values of resistors and capacitors.

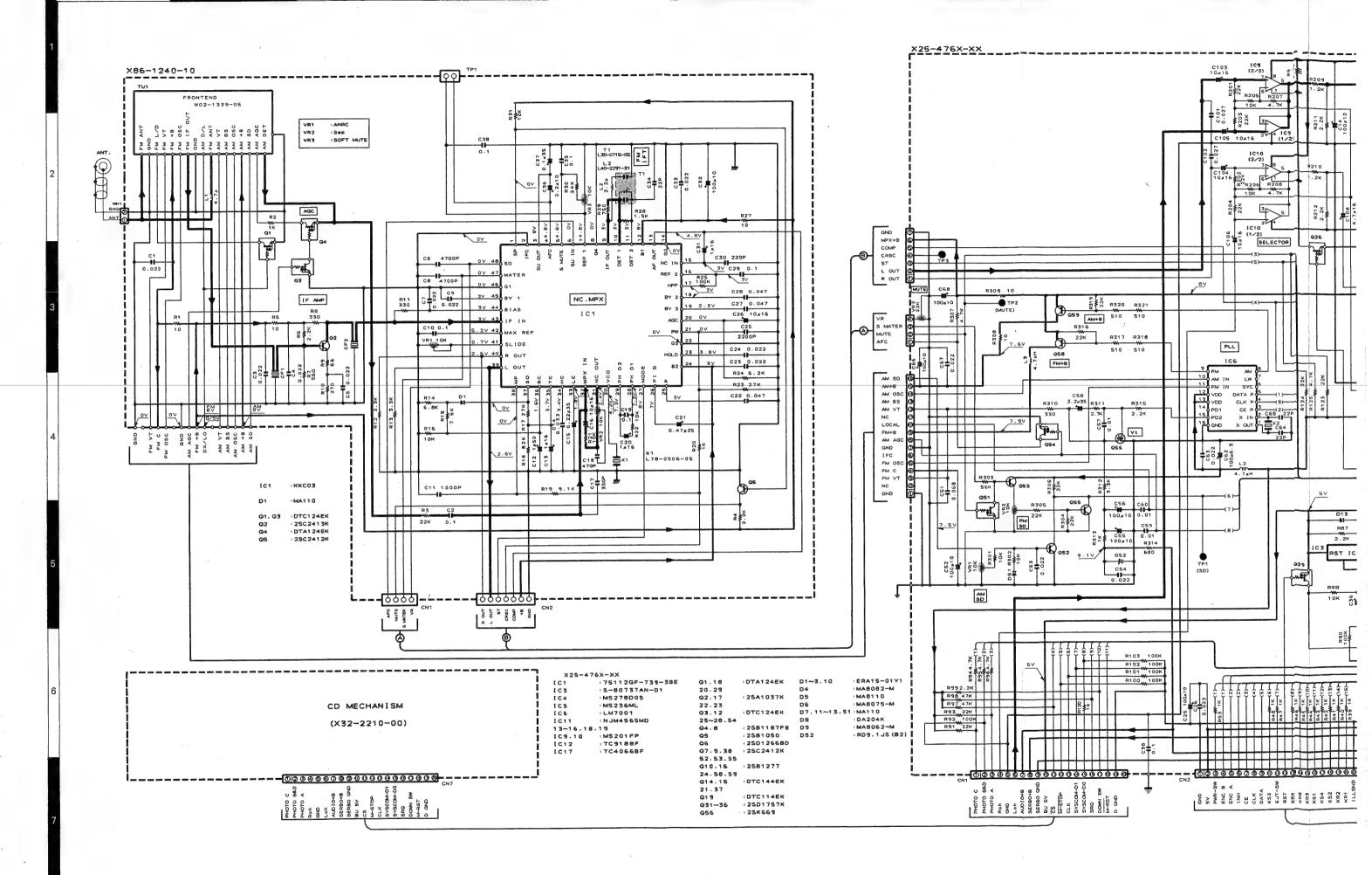


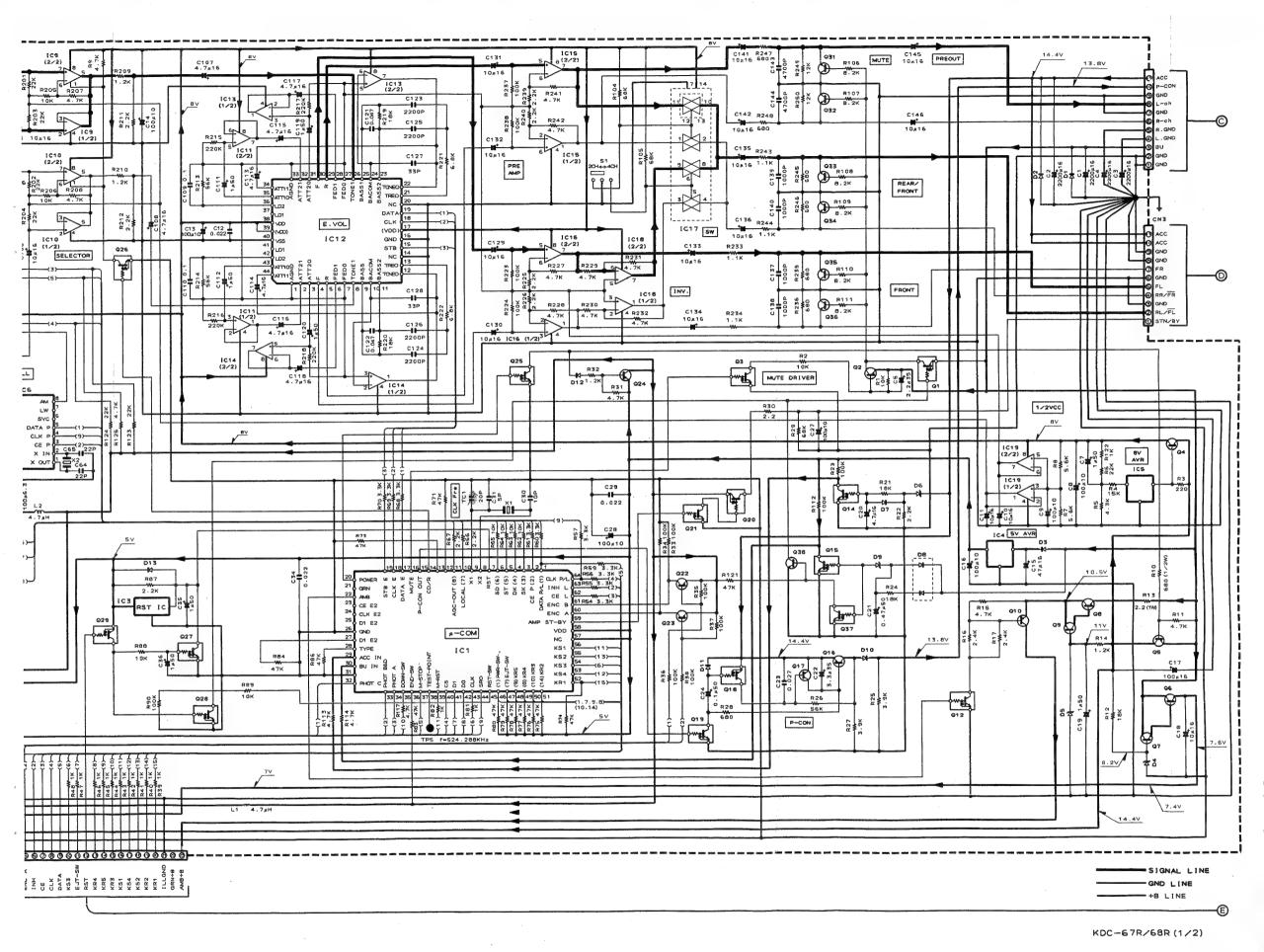






Refer to the schematic diagram for the values of resistors and capacitors.

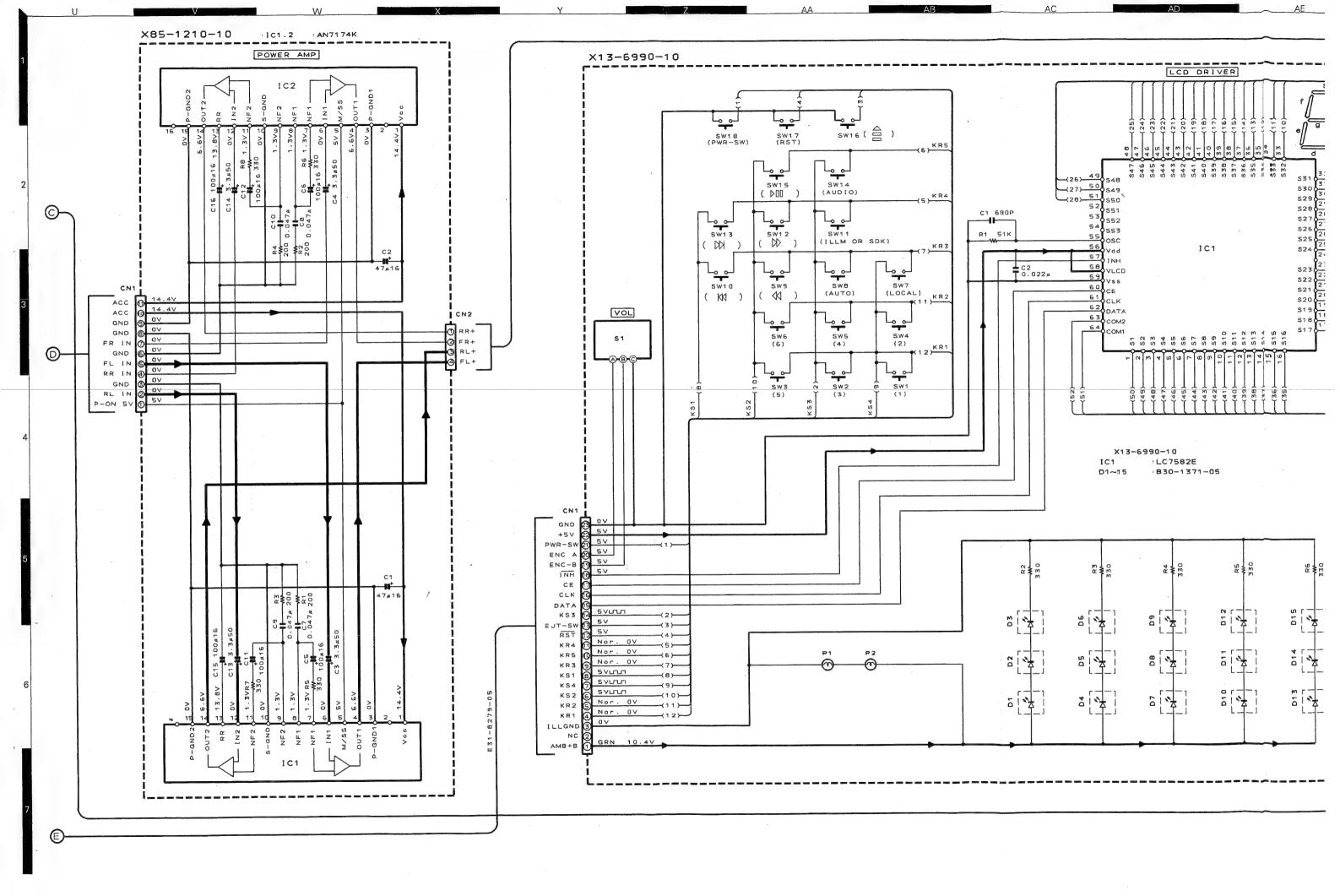


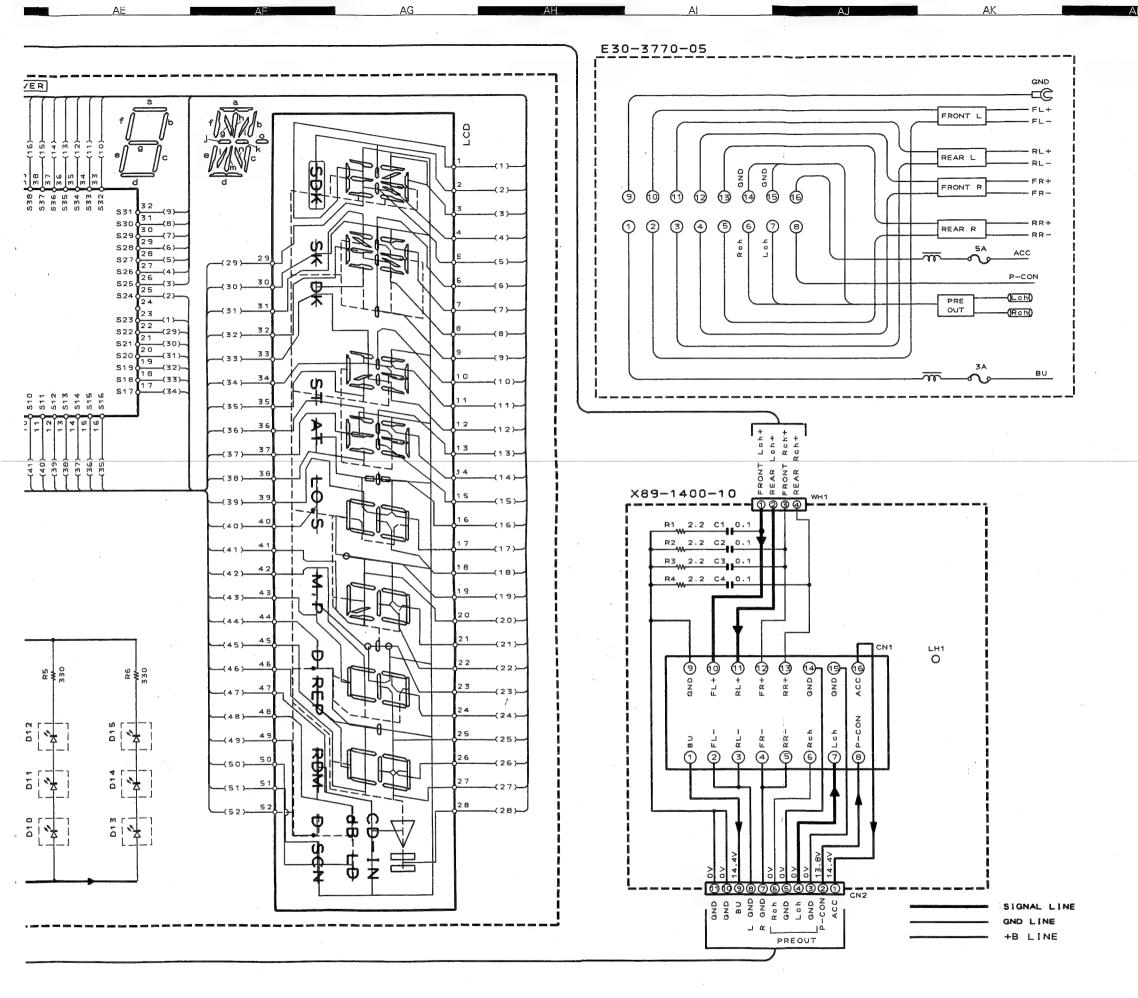


 DC voltages are as measured with a high impedance voltmeter. Values may vary slightly due to variations between individual instruments or/and units.

CAUTION: For continued safety, replace safety critical components only with manufacturer's recommended parts (refer to parts list). \triangle Indicates safety critical components. To reduce the risk of electric shock, leakage-current or resistance measurements shall be carried out (exposed parts are acceptably insulated from the supply circuit) before the appliance is returned to the customer.

KDC-67R/68R KENWOOD





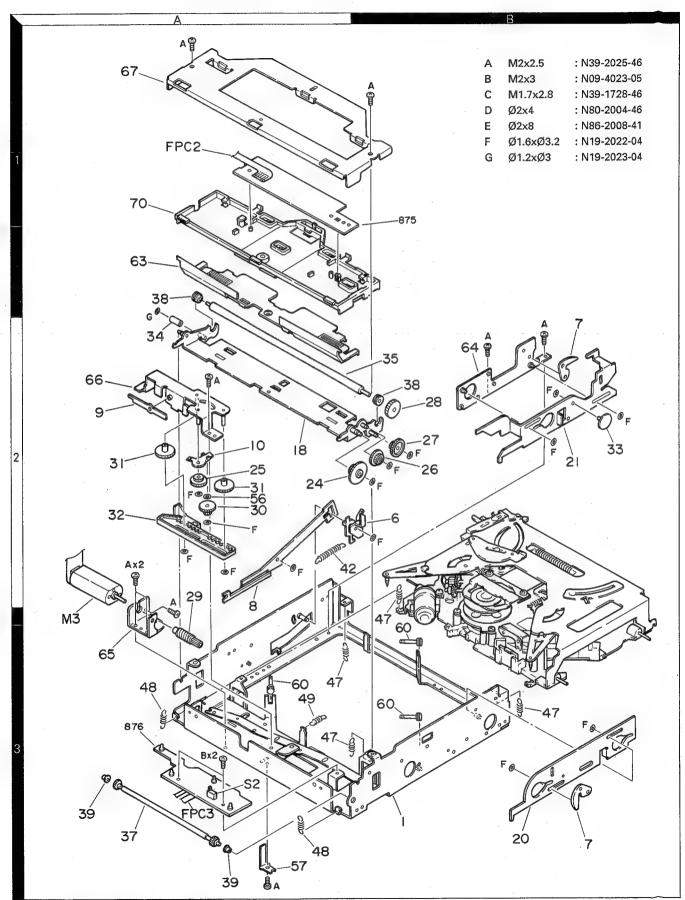
 DC voltages are as measured with a high impedance voltmeter. Values may vary slightly due to variations between individual instruments or/and units.

CAUTION: For continued safety, replace safety critical components only with manufacturer's recommended parts (refer to parts list). △ Indicates safety critical components. To reduce the risk of electric shock, leakage-current or resistance measurements shall be carried out (exposed parts are acceptably insulated from the supply circuit) before the appliance is returned to the customer.

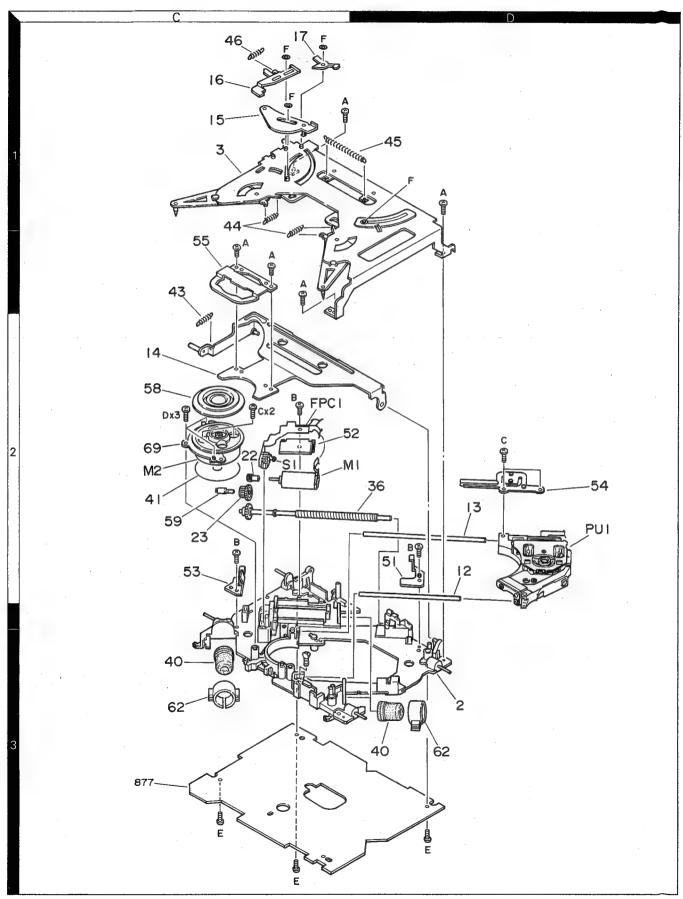
KDC-67R/68R (2/2)

KDC-67R/68R KENWOOD

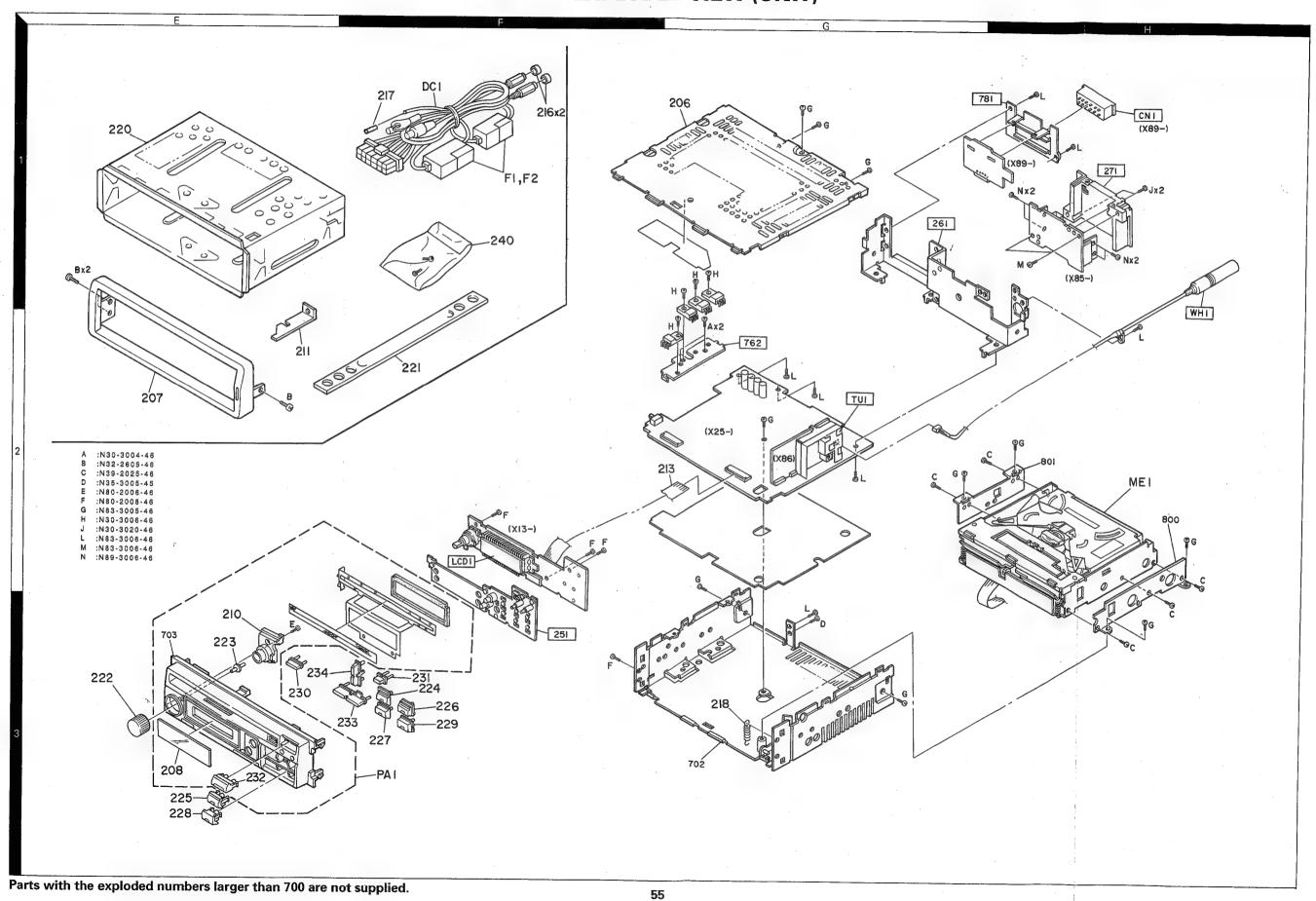
EXPLODED VIEW (MECHANISM)



EXPLODED VIEW (MECHANISM)



KDC-67R/68R KDC-67R/68R **EXPLODED VIEW (UNIT)**



KDC-67R/68R KDC-67R/68R

× New Parts

PARTS LIST

Parts without Parts No. are not supplied.

Les articles non mentionnes dans le Parts No. ne sont pas fournis.

Telle ohne Parts No. werden nicht geliefert.

Ref. No.	Address	New Parts		arts	No	•	Description	Desti- nation	Re-
参照番号	位 置	新		品	番	号	部品名/規格		備考
						KD	C-67R/68R	•	
206 PA1 PA1	1G 3F 3F	* * *	A52-06 A20-7 A20-7	775	-12		TOP PLATE PANEL ASSY (KDC-67R) PANEL ASSY (KDC-68R)	67R 68R	
207 208 208 210	2E 3E 3E 3E	* *	B07-20 B10-14 B10-14 B19-08 B46-03	168- 169- 397-	-03 -03 -02		ESCUTCHEON FRONT GLASS (KDC-67R) FRONT GLASS (KDC-68R) LIGHTING BOARD WARRANTY CARD	67R 68R	
- - -		*	B46-01 B58-12 B64-01 B64-01	213- 144-	-04 -00		QUESTIONAIRE CARD (KDC-67R) CAUTION CARD (KDC-67R) INSTRUCTION MANUAL (KDC-67R) INSTRUCTION MANUAL (KDC-68R)	67R 67R 67R 68R	
211	2F		D10-25	548-	-14		LEVER		
213)C1	2G 1F	*	E31-82 E30-37				WIRING HARNESS DC POWER CORD		
216 217 71 72	1F 1F 1F 1F	*	F29-06 F29-06 F06-50 F06-30	04- 024-	-15 -05		CAP (RCA CORD) INSULATING COVER (ANT. CONT.) FUSE (5A) ACC FUSE (3A) BU		
218	3G		G01-20	040-	-04		EXTENSION SPRING		
- - - -		* * * *	H01-93 H01-93 H03-34 H03-34 H10-44	375- 135- 137-	-04 -04 -04		ITEM CARTON CASE (KDC-67R) ITEM CARTON CASE (KDC-68R) QUTER CARTON CASE (KDC-67R) QUTER CARTON CASE (KDC-68R) POLYSTYRENE FOAMED FIXTURE	67R 68R 67R 68R	
• •			H25-03 H25-03				PROTECTION BAG (280X450X0.03) PROTECTION BAG (170X250X0.03)		
220 221	1E 2F	*	J21-72 J54-00				MOUNTING HARDWARE STAY		
222 223 224 225 226	38 38 3F 38 3F	*	K23-10 K24-06 K24-09 K24-09 K24-09	35- 907- 908-	-04 -13 -13		KNOB (VOL) KNOB (RESET) KNOB (1) KNOB (2) KNOB (3)		-
227 228 229 230 231	3F 3E 3F 3F 3F	*	K24-09 K24-09 K24-09 K24-10 K24-10)11-)12-)22-	-13 -13 -04		KNOB (4) KNOB (5) KNOB (6) KNOB (AUDIO) KNOB (EJECT)		
232 233 234	3E '* 3F '* 3F	*	K24-10 K24-10 K25-05	34-	04		KNOB (PLAY/PAUSE) KNOB (CLOCK/TUN) KNOB (FM/AM)		
240 A 3	1F 2G 1E,2E 2H,3H 3G		N99-15 N30-30 N32-26 N39-20 N35-30	04- 05- 125-	46 46 46		SCREW SET PAN HEAD MACHIN SCREW FLAT HEAD MACHIN SCREW BINDING HEAD MACHIN SCREW BINDING HEAD MACHIN SCREW		
	3F 2F,2G		N80-20 N80-20				PAN HEAD TAPTITE SCREW PAN HEAD TAPTITE SCREW		

67R : KDC-67R 68R : KDC-68R → New Parts

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Ref. No.	Address	New Parts		arts	No.		Descriptio	n	Desti- nation	Re-
参照番号	位置	新		品	番号	部	品 名/ 为	格		備
G	2H,3H		N83-30	05-	46	PAN HEAD TA	APTITE SC	REW		
ME1	2H	*	X92-16	60-	-00	MECHANISM A	ASSY			
				S	WITCH	JNIT : X13-69	990-10			
D1 -15	0.5	*	B30-13			LED	700 2 7			
LCD1 PL1 ,2	2F	*	B38-05 B30-13			LIQUID CRYS	(5.5)	V .125A)		· .
C1 C2			CK73EB			CHIP C	680PF 0.022U	K F K		
251	3F	*	E29-13	62-	02	CONDUCTIVE	RUBBER			
R1 R2 -6			RK73EB RK73EB			CHIP R	51K 330	J 1/8W J 1/8W		
51	-	:	T99-04	03-	05	SPEED DETEC	T o R			
IC1	<u> </u>	*	LC7582	_		IC			<u> </u>	
					ו או דואנ	MECHANISM		70-00		
			PT-461		10177 IN 1	PHOTO TRANS		20.00		<u> </u>
		WB *	B30-13			VECHANISM	i : X13-708	50-00		
-		1					_	•		
52	3A	<u> </u>	S40-11			PUSH SWITCH				
26.1	14.17	T u				NIT : X25-47	00-10			_
261	1H	*	A23-50	48-	0.5	REAR PANEL				
C1 -4 C5			C90-25			ELECTRO	2200UF 2.2UF	16WV 35WV		
C7			C90-26	08-	05	ELECTRO	1.0UF	50WV 10WV		
08 ,9 010 ,11		*	CE04CW C90-25			ELECTRO ELECTRO	100UF 10UF	16WV		
012			CK73FB			CHIP C	0.0220			
013 ,14 015			CEO4CW			ELECTRO ELECTRO	100UF 47UF	10WV 16WV		
016			CE04CW	1A1	01M	ELECTRO	100UF	10WV		
017			CEO4NW			ELECTRO	100UF	16WV		
C18 C19		*	C90-25 CE04NW			ELECTRO ELECTOR	10UF 1.0UF	16WV 50WV		
020 021		*	C90-25 C90-26			ELECTRO ELECTRO	4.7UF 0.47UF	16WV 50WV		
022		*	C90-26			ELECTRO	3.3UF	35WV		
223			CK73FB			CHIP C	0.0270			
02 4 025		*	C90-26 CE04CW			ELECTRO ELECTRO	0.1UF 100UF	50WV 10WV		
026 027 ,28			CK73FB CE04CW			CHIP C ELECTRO	0.022U 100UF	F K 10WV		
029			CK73FB	1H2	23KTA	CHIP C	0.0220	F K		
030 031			CC73FC	H1H	100D	CHIP C	10PF 5PF	D C		
C34			CK73FB	1H2	23KTA	CHIP C	0.0220	F K		
C35			CC73FC	H1H	560J	CHIP C	56PF	J		
			CEO4NW	1H0	10M	ELECTOR	1.0UF	50WV		
C36 C38			CK73EB	1 57 4	O'A K	CHIP C	0.10UF	К		Į.

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Ref. No.	Address		Parts No.	Description	Desti-	Re-
参照 番号	位 置	Parts 新	部品費号	部 品 名 / 規 格	nation 仕 向	mark 備考
052 053 ,54 055 ,56 057		*	CE04NW1A101M CK73FB1H223KTA CE04NW1A101M C91-2040-05 C90-2600-05	ELECTRO 100UF 10WV CHIP C 0.022UF K ELECTRO 100UF 10WV CERAMIC 0.010UF Z ELECTRO 2.2UF 35WV		
059 ,60 062 063 064 ,65			CK73FB1H103K CE04NW0J101M CK73FB1H223KTA CC73FCH1H220J CE04NW1A101M	CHIP C 0.010UF K ELECTRO 100UF 6.3WV CHIP C 0.022UF K CHIP C 22PF J ELECTRO 100UF 10WV		
067 068 0101,102 0103-106 0107,108		*	CK73FB1H223KTA CE04NW1A101M CK73FB1E273KTA C90-2597-05 C90-2595-05	CHIP C 0.022UF K ELECTRO 100UF 10WV CHIP C 0.027UF K ELECTRO 10UF 16WV ELECTRO 4.7UF 16WV		
2109,110 2111,112 2113-118 2119,120 2121,122		*	CK73EB1E104K C90-2608-05 C90-2595-05 C90-2608-05 CK73EB1H473K	CHIP C 0.10UF K ELECTRO 1.0UF 50WV ELECTRO 4.7UF 16WV ELECTRO 1.0UF 50WV CHIP C 0.047UF K		
0123-126 0127,128 0129-136 0137-140 0141,142		*	CK73FB1H222K CC73FSL1H330J C90-2597-05 CK73FB1H102K C90-2597-05	CHIP C 2200PF K CHIP C 33PF J ELECTRO 10UF 16WV CHIP C 1000PF K ELECTRO 10UF 16WV		
C143,144 C145,146 TC1		*	C93-1036-05 C90-2597-05 C05-0510-05	CERAMIC 4700PF K ELECTRO 10UF 16WV CERAMIC TRIMMER CAPACITOR(20P	F	
L1 -3 X1 X2			L40-4791-31 L77-1167-05 L77-1166-05	SMALL FIXED INDUCTOR(4.7UH) CRYSTAL RESONATOR CRYSTAL RESONATOR		
Н Ј	1G,2G 1H 1H,2G	*	N30-3006-46 N30-3020-46 N83-3006-46	PAN HEAD MACHIN SCREW PAN HEAD MACHIN SCREW BINDING HEAD TAPTITE SCREW		
R1 ,2 R3 R4 R5 R6			RK73FB2A103J RK73FB2A221J RK73FB2A153J RK73FB2A432J RK73FB2A223J	CHIP R 10K J 1/10 CHIP R 220 J 1/10 CHIP R 15K J 1/10 CHIP R 4.3K J 1/10 CHIP R 22K J 1/10	₩ ₩ ₩	
R7 ,8 R9 R10 R11 R12			RK73EB2B562J RK73FB2A472J R92-2063-05 RK73FB2A472J RK73FB2A183J	CHIP R 5.6K J 1/8W CHIP R 4.7K J 1/10 CHIP R 680 J 1/2W CHIP R 4.7K J 1/10 CHIP R 18K J 1/10	W	
R13 R14 R15 R16 ,17			R92-2104-05 RK73EB2B122J RK73FB2A472J RK73FB2A242J RK73FB2A183J	CHIP R 2.2 J 1W CHIP R 1.2K J 1/8W CHIP R 4.7K J 1/10 CHIP R 2.4K J 1/10 CHIP R 18K J 1/10	W	
R22 R23 R24 R25 R26			RK73FB2A222J RK73FB2A104J RK73FB2A183J RK73FB2A392J RK73FB2A563J	CHIP R 2.2K J 1/10 CHIP R 100K J 1/10 CHIP R 18K J 1/10 CHIP R 3.9K J 1/10 CHIP R 56K J 1/10	₩ ₩ ₩:	

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Ref. No.	Address		Parts	No.		Descriptio	n		Desti-	Re-
参照番号	位置	Parts 新	部品	番 号	部	品名/#	見格			mark 備考
R27 R28 R29 R30 R31			RK73FB2A R92-2063 RK73FB2A RK73FB2A RK73FB2A	-05 683J 2R2J	CHIP R CHIP R CHIP R CHIP R	3.9K 680 68K 2.2 4.7K	J J J	1/10W 1/2W 1/10W 1/10W 1/10W		
R32 R33 -38 R39 -48 R53 R54 -57			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	104J 102J 102J	CHIP R CHIP R CHIP R CHIP R CHIP R	1.2K 100K 1.0K 1.0K 3.3K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R59 -61 R62 -65 R66 ,67 R68 -70			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	103J 222J 332J	CHIP R CHIP R CHIP R CHIP R	3.3K 10K 2.2K 3.3K 47K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
773 -80 81 ,82 83 84 86			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	102J 473J 473J	CHIP R CHIP R CHIP R CHIP R	47K 1.0K 47K 47K 47K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
887 888 ,89 890 891			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	103J 104J 223J	CHIP R CHIP R CHIP R CHIP R	2.2K 10K 100K 22K 100K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R93 R94 -96 R97 ,98 R99 R100-103			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	472J 473J 222J	CHIP R CHIP R CHIP R CHIP R	22K 4.7K 47K 2.2K 100K]]]	1/10W 1/10W 1/10W 1/10W 1/10W		
R104,105 R106-111 R112 R113-119 R113,114			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	822J 104J 203J	CHIP R CHIP R CHIP R CHIP R CHIP R	68K 8.2K 100K 20K 4.7K]]]	1/10W 1/10W 1/10W 1/10W 1/10W		
R117 R120 R121 R122 R123,124			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	102J 473J 102J	CHIP R CHIP R CHIP R CHIP R CHIP R	4.7K 1.0K 47K 1.0K 22K	J	1/10W 1/10W 1/10W 1/10W 1/10W		
1125 2201-204 2205,206 2207,208 2209,210			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	223J 103J 472J	CHIP R CHIP R CHIP R CHIP R CHIP R	4.7K 22K 10K 4.7K 1.2K]]] J	1/10W 1/10W 1/10W 1/10W 1/10W		
R211,212 R213,214 R215-218 R219,220 R221,222			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	563J 224J 183J	CHIP R CHIP R CHIP R CHIP R CHIP R	2.2K 56K 220K 18K 6.8K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
223,224 2225,226 227-232 233,234 235,236			RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	222J 472J 112J	CHIP R CHIP R CHIP R CHIP R CHIP R	100K 2.2K 4.7K 1.1K 680	J J J J	1/10W 1/10W 1/10W 1/10W 1/10W		

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Ref.	No.	Add	ress		Part	s No.	1	Description			Desti- nation	Re-
参照	番号	位	潼	Parts 新	部品	番号	部。	品 名/規	格			mark! 備考
R237,2 R239,2 R241,2 R243,2 R245-2	240 242 244				RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	1222J 1472J 112J	CHIP R CHIP R CHIP R CHIP R CHIP R	100K 2.2K 4.7K 1.1K 680	J J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R249,2 R301,3 R303 R304-3 R307	302				RK73FB2/ RK73FB2/ RK73FB2/ RK73FB2/ RK73FB2/	1103J 1563J 1223J	CHIP R CHIP R CHIP R CHIP R CHIP R	12K 10K 56K 22K 4.7K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R308,3 R310 R311 R312 R313	309			المدادات المساورة والمساورة والمساور	RK73FB2A RK73FB2A RK73FB2A RK73FB2A RK73FB2A	A331J A272J A332J	CHIP R CHIP R CHIP R CHIP R CHIP R	10 330 2.7K 3.3K 1.0K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R314 R315 R316 R317,3	318				RK73FB2A RK73FB2A RK73FB2A RK73EB2E RK73FB2A	A222J A223J B511J	CHIP R CHIP R CHIP R CHIP R CHIP R	680 2.2K 22K 510 22K	J J J	1/10W 1/10W 1/10W 1/8W 1/10W		
R320,3 VR1 ,2 VR3 W1 -4	2				RK73EB2E R12-6423 R12-6425 R92-2053	3-05 5-05	CHIP R TRIM POT. TRIM POT. CHIP R	510 10K 22K 0	J	1/8W		
51					562-0803	3-05	SLIDE SWITCH	н				
D1 -3 D4 D5 D6 D7	3				ERA15-01 MA8082-N MA8110 MA8075-N MA110	1	DIODE ZENER DIODE ZENER DIODE ZENER DIODE DIODE	·				
D8 D9 D10 D11 -:	13				DA204K MA8062-I ERA15-01 MA110 MA110		DIODE ZENER DIODE DIODE DIODE DIODE					
D52 IC1 IC3 IC4 IC5				*	RD9.1JS0 75112GF- S-80737/ M5278D09 M5236ML	-739-3BE AN-D1	ZENER DIODE IC IC IC(VOLTAGE IC(VOLTAGE					
IC6 IC9 ,: IC11 IC12 IC13-:					LM7001 M5201FP NJM4565N TC9188F NJM4565N		IC(PLL FREQUENCE OF AMPLIED OF AM	FIER) 2) Tric Volui		IZER)		
IC17 IC18,: Q1 Q2 Q3	19				TC4066BI NJM4565I DTA124EI 2SA1037I DTC124EI	MD K K	IC(BILATERA IC(OP AMP X DIGITAL TRA TRANSISTOR DIGITAL TRA	2) NSISTOR	(4)			
Q4 Q5 Q6 Q7					2SB11870 2SB1050 2SD12660 2SC24120	BD	TRANSISTOR TRANSISTOR TRANSISTOR TRANSISTOR					

⚠印は安全部品

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参照番号	位置	新	部品番号	部品名/制	格		備考
Q8 Q9 Q10 Q12 Q14 ,15	To the second se	*	2SB1187F8 2SC2412K 2SB1277 DTC124EK DTC144EK	TRANSISTOR TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR DIGITAL TRANSISTOR			
Q16 Q17 Q18 Q19 Q20		*	2SB1277 2SA1037K DTA124EK DTC114EK DTA124EK	TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR DIGITAL TRANSISTOR DIGITAL TRANSISTOR DIGITAL TRANSISTOR			
921 922 ,23 924 925 -28 929		*	DTC144EK 2SA1037K 2SB1277 DTC124EK DTA124EK	DIGITAL TRANSISTOR TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR DIGITAL TRANSISTOR			
Q31 -36 Q37 Q38 Q51 Q52 ,53			2SD1757K DTC144EK 2SC2412K DTC124EK 2SC2412K	TRANSISTOR DIGITAL TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR TRANSISTOR			
Q54 Q55 Q56 Q58 ,59		*	DTC124EK 2SC2412K 2SK669 2SB1277	DIGITAL TRANSISTOR TRANSISTOR FET TRANSISTOR			
	C	D F	PLAYER UNIT IN M	IECHANISM ASS'Y : X	32-2210-00		
C1 C2 C3 C4 C5			CK73FB1H103K CC73FCH1H220J CC73FCH1H020C CK73FB1H103K CK73FB1E473KTA	CHIP C 0.010UE CHIP C 22PF CHIP C 2.0PF CHIP C 0.010UE CHIP C 0.047UE	J C K		
C6 C7 C8 C9 C10 ,11			CC73FCH1H181J CK73FB1H223KTA CK73FB1E393KTA C92-1025-05 C92-1020-05	CHIP C 180PF CHIP C 0.022UF CHIP C 0.039UF ELECTRO 0.47UF BLECTRO 10UF			
C12 C13 C14 C15 C16		*	CK73FB1H153K CK73FB1H223KTA C92-1020-05 C92-1026-05 C92-1023-05	CHIP C 0.015UF CHIP C 0.022UF ELECTRO 10UF ELECTRO 1UF ELECTRO 22UF			
C18 C20 ,21 C22 ,23 C24 C25 ,26			CK73EF1C105Z CK73EF1C105Z CK73FB1E393KTA CC73FCH1H101J CK73FB1H103K	CHIP C 1.0UF CHIP C 1.0UF CHIP C 0.039UF CHIP C 100PF CHIP C 0.010UF	J		
C27 ,28 C29 ,30 C32 C33 C35			CK73EF1C105Z CC73FCH1H330J CK73EB1E104K CK73EB1E224K CC73FCH1H560J	CHIP C 1.0UF CHIP C 33PF CHIP C 0.10UF CHIP C 0.22UF CHIP C 56PF	Z J K K J		
C38 C41 ,42 C45 C47 C48		*	CK73FB1H102K CC73FCH1H100D C92-0012-05 C92-1026-05 C92-1019-05	CHIP C 1000PF CHIP C 10PF TANTAL 22UF ELECTRO 1UF ELECTRO 4.7UF	K D 6.3WV 50WV 16WV		

* New Parts

PARTS LIST

Parts without Parts No. are not supplied.

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Ref. No.	Address		Parts No.		Description		Desti-	Re-
参照番号	位置	Parts 新	部品番号	部	品 名/規	格		mark
C49 C60 ,61 C66 C67 C68			CK73FB1H183KTA CK73EB1E104K CK73FB1H102K CK73FB1H103K CK73FB1H102K	CHIP C CHIP C CHIP C CHIP C CHIP C	0.018UF 0.10UF 1000PF 0.010UF 1000PF	K K K K		
C101 C103 C105-108 C109,110 C111,112			CK73FB1H331K CK73FB1H331K CC73FCH1H181J CK73FB1H221K C92-1019-05	CHIP C CHIP C CHIP C CHIP C ELECTRO	330PF 330PF 180PF 220PF 4.7UF	K K J K 16WV		
C113,114 C115,116 C117 C118,119 C120,121			CK73FB1H182K C92-1019-05 C92-1020-05 CK73EB1E104K CK73FB1H102K	CHIP C ELECTRO ELECTRO CHIP C CHIP C	1800PF 4.7UF 10UF 0.10UF 1000PF	K 16WV 6.3WV K K		
C122 C123			CK73EB1E104K CK73FB1E473KTA	CHIP C	0.10UF 0.047UF	K K		
L1 L2 L3 .4 X1 X2			L33-0916-05 L40-1001-31 L33-0916-05 L78-0505-05 L77-2011-05	SMALL FIXED SMALL FIXED SMALL FIXED RESONATOR CRYSTAL RESO	INDUCTOR (INDUCTOR			
R1 R2 R3 R4 R5			RK73FB2A102J RK73EB2B100J RK73FB2A332J RK73FB2A472J RK73FB2A153J	CHIP R CHIP R CHIP R CHIP R CHIP R	1.0K 10 3.3K 4.7K 15K	J 1/10W J 1/8W J 1/10W J 1/10W J 1/10W		
R6 R7 R8 R9 R10			RK73FB2A910J RK73FB2A241J RK73FB2A562J RK73FB2A134J RK73FB2A822J	CHIP R CHIP R CHIP R CHIP R CHIP R	91 240 5.6K 130K 8.2K	J 1/10W J 1/10W J 1/10W J 1/10W J 1/10W		
R11 R12 R13 ,14 R16 R17			RK73FB2A123J RK73FB2A223J RK73FB2A123J RK73FB2A331J RK73FB2A223J	CHIP R CHIP R CHIP R CHIP R	12K 22K 12K 330 22K	J 1/10W J 1/10W J 1/10W J 1/10W J 1/10W		
R18 R19 R20 R21 R22			RK73FB2A391J RK73FB2A272J RK73FB2A122J RK73FB2A125J RK73FB2A471J	CHIP R CHIP R CHIP R CHIP R CHIP R	390 2.7K 1.2K 1.2M 470	J 1/10W J 1/10W J 1/10W J 1/10W J 1/10W		
R23 R24 ,25 R26 ,27 R28 R29			RK73FB2A103J RK73EB2B222J RK73FB2A102J RK73FB2A333J RK73FB2A154J	CHIP R CHIP R CHIP R CHIP R CHIP R	10K 2.2K 1.0K 33K 150K	J 1/10W J 1/8W J 1/10W J 1/10W J 1/10W		
R30 R34 R35 R36 R37			RK73FB2A154J RK73FB2A221J RK73EB2B472J RK73FB2A562J RK73FB2A474J	CHIP R CHIP R CHIP R CHIP R CHIP R	150K 220 4.7K 5.6K 470K	J 1/10W J 1/10W J 1/8W J 1/10W J 1/10W		
R38 R39			RK73EB2B103J RK73FB2A103J	CHIP R CHIP R	1 OK 1 OK	J 1/8W J 1/10W		

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Ref. No.	Address	New	Parts No.		Description			Desti- nation	Re-
参照番号	位置	新	部品番号	部	品 名/規	格			備考
R40 ,41 R42 R43 R44			RK73FB2A472J RK73FB2A104J RK73FB2A224J RK73FB2A822J RK73FB2A272J	CHIP R CHIP R CHIP R CHIP R CHIP R	4.7K 100K 220K 8.2K 2.7K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R46 R47 R48 R49 R50			RK73FB2A183J RK73FB2A393J RK73FB2A102J RK73FB2A331J RK73FB2A473J	CHIP R CHIP R CHIP R CHIP R CHIP R	18K 39K 1.0K 330 47K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R51 R52 R53 R55 R56			RK73FB2A224J RK73FB2A225J RK73FB2A333J RK73FB2A103J RK73FB2A122J	CHIP R CHIP R CHIP R CHIP R	220K 2.2M 33K 10K 1.2K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R60 R61 -63 R65 R66 R67			RK73FB2A272J RK73FB2A103J RK73FB2A563J RK73FB2A104J RK73FB2A273J	CHIP R CHIP R CHIP R CHIP R CHIP R	2.7K 10K 56K 100K 27K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R68 R69 R70 R71 R72			RK73FB2A123J RK73FB2A183J RK73FB2A433J RK73FB2A223J RK73FB2A104J	CHIP R CHIP R CHIP R CHIP R CHIP R	12K 18K 43K 22K 100K	J J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R73 -76 R77 R78 R79 R80			RK73FB2A223J RK73EB2B223J RK73FB2A103J RK73FB2A332J RK73EB2B223J	CHIP R CHIP R CHIP R CHIP R	22K 22K 10K 3.3K 22K	J J J	1/10W 1/8W 1/10W 1/10W 1/8W		
R81 R82 -85 R86 R87 R88			RK73FB2A102J RK73FB2A104J RK73FB2A184J RK73FB2A333J RK73EB2B563J	CHIP R CHIP R CHIP R CHIP R CHIP R	1.0K 100K 180K 33K 56K	J J J	1/10W 1/10W 1/10W 1/10W 1/8W		
R89 R90 R91 R92 R93 -95			RK73EB2B683J RK73FB2A103J RK73FB2A333J RK73EB2B683J RK73FB2A331J	CHIP R CHIP R CHIP R CHIP R CHIP R	68K 10K 33K 68K 330	J J J	1/8W 1/10W 1/10W 1/8W 1/10W		
R96 ,97 R98 R99 R101-108			RK73FB2A223J RK73EB2B220J RK73FB2A222J RK73FB2A472J RK73FB2A822J	CHIP R CHIP R CHIP R CHIP R	22K 22 2.2K 4.7K 8.2K	J J J	1/10W 1/8W 1/10W 1/10W 1/10W		
R113,114 R115,116 R117,118 R121,122		-	RK73FB2A562J RK73FB2A682J RK73FB2A562J RK73FB2A681J RK73FB2A223J	CHIP R CHIP R CHIP R CHIP R CHIP R	5.6K 6.8K 5.6K 680 22K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R125,126 R127 R128 R151 R153			RK73FB2Å103J RK73FB2A561J RK73FB2A102J RK73FB2A102J RK73FB2A682J	CHIP R CHIP R CHIP R CHIP R	10K 560 1.0K 1.0K 6.8K	J J J J	1/10W 1/10W 1/10W 1/10W 1/10W		

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Ref. No.	Address	New Parts 新	Parts No. 部品番号	Description 部 品 名 / 規 格	nation	Re- mark 備考
2 M 2 2	1111	भा	即 明 罗 亏	即用11/22作	II [a]	789 1
R154 R156 VR1 VR2 W1 ,2			RK73FB2A225J RK73FB2A221J R12-6423-05 R12-6429-05 R92-2052-05	CHIP R 2.2M J 1/10W CHIP R 220 J 1/10W TRIM POT. 10K TRIMMING POT.(100K) CHIP R 0 J 1/10W		
W4 -7 W11 -25			R92-2052-05 R92-2053-05	CHIP R 0 J 1/10W CHIP R 0 J 1/8W		
D1 D2 D3 D4 D6 -8			MA110 MA8062 MA110 MA8091 MA110	DIODE ZENER DIODE DIODE ZENER DIODE DIODE		
IC1 IC2 IC3 IC5 IC6		*	TA8191F TC9236AF AN8388SR TA7291F 75008GB-672-3B4	IC(CD FOUCUS, TRACKING SERVO) IC(CD 1CHIP PROCESSOR) IC IC IC		
IC7 IC8 ,9 IC11 IC12 IC13		*	SM5870AS NJM4580E TA78L05F TC7SU04F TC74AC04F	IC IC(OP AMP) IC(VOLTAGE REGULATOR/ +5V) IC(INVERTER) IC		
91 92 93 94 95			2SB624(BV3) 2SA1037K DTC124EK 2SC2412K DTA124EK	TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR		
97 ,8 99 910 911 912			DTC114YK 2SA1037K 2SC2412K DTC114YK DTC124EK	DIGITAL TRANSISTOR TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR DIGITAL TRANSISTOR		
913 914 915 916 ,17 918 -20			2SA1036K 2SD1624 DTA124EK 2SD1757K DTC124EK	TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR TRANSISTOR DIGITAL TRANSISTOR		
TH1			NT732BTD33K	THERMISTOR		
****				R UNIT : X85-1210-10		
01 ,2 03 04 05 ,6 07 -10		*	C90-2552-05 C90-2556-05 C90-2556-05 C90-2564-05 CK73EB1H473K	ELECTRO 47UF 16WV ELECTRO 3.3UF 50WV ELECTRO 3.3UF 50WV ELECTRO 100UF 16WV CHIP C 0.047UF K		
011 ,12 013 ,14 015 ,16) 1	C90-2564-05 C90-2556-05 C90-2564-05	ELECTRO 100UF 16WV ELECTRO 3.3UF 50WV ELECTRO 100UF 16WV		
271	1H	*	F01-1391-03	HEAT SINK		
M N	1H 1H		N83-3006-46 N89-3006-46	PAN HEAD TAPTITE SCREW BINDING HEAD TAPTITE SCREW		
R1 -4 R5 -8			RK73EB2B201J RK73EB2B331J	CHIP R 200 J 1/8W CHIP R 330 J 1/8W		

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Ref. No.	Address	New		arts	No.		Description	12 11	Desti-	Re-
多番照卷	位置	新	部	品	番 号	部	品名/規	格	nation 仕 向	marks
W5 W6 -16			R92-20 R92-20			CHIP R	0	J 1/10W J 1/8W		
IC1 ,2		<u></u>	AN7174	1K		IC(AF AMP)				
						VIT : X86-124				
C1 C2 C3 -5 C6 C7			CK73FI CK73FI CK73FI CK73FI	31E1 31H2 31H4	04K 23KTA 72K	CHIP C CHIP C CHIP C CHIP C	0.022UF 0.10UF 0.022UF 4700PF 0.022UF	K K K K K		
C8 C9 C10 C11 C12			CK73EI CK73EI CK73EI CK73EI CE04N	31H2 31E1 31H1	23KTA 04K 02K	CHIP C CHIP C CHIP C CHIP C ELECTOR	4700PF 0.022UF 0.10UF 1000PF 1.0UF	K K K Sowv		
C13 C14 C15 C16 C17			C92-00 CK73EI C92-00 CE04NI CK73FI	81H3 002- V1C1	93K 05 00M	ELECTRO CHIP C CHIP TAN ELECTRO CHIP C	1.0UF 0.039UF 0.22UF 10UF 330PF	16WV K 35WV 16WV K		
C18 C19 C20 C21 C22			CK73FI CK73EI C92-00 C92-00 CK73EI	31E1 004- 003-	04K 05 05	CHIP C CHIP C ELECTRO CHIP TAN CHIP C	470PF 0.10UF 1.0UF 0.47UF 0.047UF	K K 16WV 25WV K		
C23 ,24 C25 C26 C27 ,28 C29			CK73FE CK73FE CE04NV CK73EE CK73EE	31H2 V1C1 31H4	22K 00M 73K	CHIP C CHIP C ELECTRO CHIP C CHIP C	0.022UF 2200PF 10UF 0.047UF 0.10UF	K K 16WV K K		
C30 C31 C32 C33 C34			CK73FE C92-00 CE04NI CK73FE CC73F0	004- V1A1 B1H2	05 01M 23KTA	CHIP C ELECTRO ELECTRO CHIP C CHIP C	220PF 1.0UF 100UF 0.022UF 22PF	K 16WV 10WV K J		
C35 C36 C37 C38			CK73EE C92-05 C92-00 CK73EE	514- 001-	05 05	CHIP C CHIP TAN CHIP TAN CHIP C	0.10UF 2.2UF 0.1UF 0.10UF	K 10WV 35WV K		
WH1	1H	*	E30-31	786-	05	CORD WITH F	PLUG		, .	
CF1 ,2 L1 L2 T1 X1		*	L72-07 L40-47 L40-22 L30-07 L78-09	791 - 291 - 715 -	16 31 05	CERAMIC FIL SMALL FIXED SMALL FIXED FM IFT RESONATOR	INDUCTOR			
R1 R2 R3 R4 R5			RK73EE RK73FE RK73FE RK73FE RK73EE	32A1 32A2 32A2	02J 23J 22J	CHIP R CHIP R CHIP R CHIP R CHIP R	10 1.0K 22K 2.2K 10	J 1/8W J 1/10W J 1/10W J 1/10W J 1/8W		
R6 R7 R8 R9			RK73FE RK73FE RK73FE RK73FE	32A5 32A3	61J 31J	CHIP R CHIP R CHIP R CHIP R	2.2K 560 330 56	J 1/10W J 1/10W J 1/10W J 1/10W		

KDC-67R/68R KDC-67R/68R

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Ref.	No.	Address	New Parts		arts	No.		De	scription			Desti- nation	Re-
参用	用番号	位置	新	部	品	番号	部	品	名/規	格			mar
R10 R11 R12 R14 R15	,13			RK73F RK73F RK73F RK73F RK73F	32A 32A 32A	331J 332J 682J	CHIP R CHIP R CHIP R CHIP R CHIP R		270 330 3.3K 6.8K 7.5K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R16 R17 R18 R19 R20				RK73FI RK73FI RK73FI RK73FI RK73FI	32A2 32A3	273J 823J 912J	CHIP R CHIP R CHIP R CHIP R CHIP R		10K 27K 82K 9.1K 1.0K	J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R21 , R23 R24 R25 R27	, 22			RK73FI RK73FI RK73FI RK73FI RK73FI	32A 32A 32A	273J 562J 104J	CHIP R CHIP R CHIP R CHIP R CHIP R		10K 27K 5.6K 100K	J J J J	1/10W 1/10W 1/10W 1/10W 1/10W		
R28 R29 R30 R31 VR1	, 2			RK73FI RK73FI RK73FI RK73FI R12-36	32A7 32A2 32A1	751J 243J 103J	CHIP R CHIP R CHIP R CHIP R TRIMMING P		1.5K 750 24K 10K (10K 7t)	J J J	1/10W 1/10W 1/10W 1/10W		
VR3 W1 -	-3			R12-31 R92-20			TRIMMING PO		(10K9 7)	J	1/8W		
D1 IC1 Q1 Q2 Q3			*	MA110 KKC03 DTC124 2SC241 DTC124	3K		DIODE IC DIGITAL TRANSISTOR DIGITAL TRANSISTOR				•,		
Q4 Q5				DTA124 2SC241		:	DIGITAL TRA	ANS	ISTOR				
TU1_		2G	*	W02-13	339-	-05	FM/AM FRON	r-E	ND				
			, ,				NIT : X89-14						
C1 -	-4	r ·		CK73EE	1E1	04K	CHIP C	(0.10UF	K			
CN1		1H		E40-91	74-	-05	PIN ASSY						
LH1				J19-28	26-	-05	HOLDER						
	-4 -3			RK73EE			CHIP R		2.2	J J	1/8W 1/8W		
				ME	CH	ANISM A	ASS'Y : X92-1						
1 2 3 6 7		3A 3D 1C 2B 2B,3B	* * * *	A10-21 A10-21 A10-21 D10-26 D10-26	24- 27- 93-	-03 -03 -04	CHASSIS CAL CHASSIS ASS CHASSIS CAL LEVER LEVER	SY					
8 9 10 12 13		2A 2A 2A 2D 2D	* * * *	D10-26 D10-26 D10-26 D10-27 D10-27	97- 98-	-04 -04 -04	LEVER LEVER ARM ASSY ROD ROD					and the state of t	
14 15 16 17		2C 1C 1C 1C	* * *	D10-27 D10-27 D10-27 D10-27	12- 14-	04 04	LEVER LEVER ASSY LEVER LEVER						

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参照番号	位置	新	部品番号	部品名/規格		備
18 20 21 22 23	2A 3B 2B 2C 2C	* * *	D10-2716-03 D12-0604-03 D12-0605-03 D13-1029-24 D13-1030-24	LEVER ASSY CAM CAM GEAR GEAR		
24 25 26 27 28	2B 2A 2B 2B 2B	*	D19-0605-04 D13-1040-04 D13-1042-44 D13-1043-04 D13-1044-24	GEAR GEAR GEAR GEAR GEAR	·.	
29 30 31 32 33	3A 2A 1A 2A 2B	* * * *	D13-1083-04 D13-1084-04 D13-1085-04 D13-1086-03 D14-0622-04	WORM GEAR GEAR LACK (GEAR) ROLLER ASSY		
34 35 36 37 38	1 A 2 A 2 D 3 A 1 A	* * *	D14-0633-04 D14-0624-03 D21-2109-04 D21-2111-04 D23-0905-14	ROLLER ROLLER SHAFT ASSY SHAFT ASSY RETAINER		
39 40 41 42 43	3A 3C,3D 2C 2A 2C	* * * * *	D23-0910-04 D39-0202-03 F20-1708-04 G01-2584-04 G01-2585-04	RETAINER DAMPER INSULATING SHEET EXTENSION SPRING EXTENSION SPRING		
44 45 46 47 48	1C 1D 1C 2B 3A	*	G01-2588-04	EXTENSION SPRING EXTENSION SPRING EXTENSION SPRING EXTENSION SPRING EXTENSION SPRING EXTENSION SPRING		
49 51 52 53 54	3A 2D 2C 2C 2D	* * *	G02-1136-04 G02-1138-04 G02-1139-04	EXTENSION SPRING FLAT SPRING FLAT SPRING FLAT SPRING FLAT SPRING ASSY		
56 57 58	1C 2A 3A 2C 2C	*	G02-1156-04 G02-1157-04 J11-0603-03	FLAT SPRING FLAT SPRING FLAT SPRING CLAMPER PIN		
62 63 64	2B	* *	J19-4411-04 J19-4412-03 J21-7268-04	PIN HOLDER HOLDER MOUNTING HARDWARE ASSY MOUNTING HARDWARE		
67 69	1 A 2C	* * *	J21-7279-02 J30-1014-04 J90-0726-02	MOUNTING HARDWARE ASSY MOUNTING HARDWARE SPACER GUIDE PROTECTION BAG (200X250X0.05)		
	1 A 3 A 2 C 2 C 3 C		N09-4023-05 N39-1728-46 N80-2004-46	PAN HEAD MACHIN SCREW MACHINE SCREW (M2X3) PAN HEAD MACHIN SCREW PAN HEAD TAPTITE SCREW BINDING HEAD TAPTITE SCREW		

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KDC-67R/68R KDC-67R/68R

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Ref.	No.	Add			ts	No.		Description Desti-	Re-
雅◆	番号	位	Parts 新		4		}	部品名/規格 供向	marks 備考
PPC1 PPC2 PPC3		2B 2C 1A 3A 2C	* *	N19-202 J84-002 J84-002 J84-002 T42-070	2-1	03 03 03		FLAT WASHER FLEXIBLE PRINTED WIRING BOARD FLEXIBLE PRINTED WIRING BOARD FLEXIBLE PRINTED WIRING BOARD DC MOTOR	
12 13 PU1 51 S2		2C 2A 2D 2C 3A	* *	T42-071 T42-072 T25-020 S40-111 S40-114	2-1	05 05 05		MOTOR ASSY DC MOTOR OPTICAL PICKUP HEAD PUSH SWITCH PUSH SWITCH	
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PARTS LIST

SPECIFICATIONS

..70dB

.....1.5dB ..40dB (1kHz)

Signal to noise ratio

Selectivity.

Disc section	
Laser diode	GaAlAs (λ=780nm)
Digital filter	4 times over sampling
D/A converter	1 bit (with D.P.A.C.)
Spindle speed	500 to 200rpm (CLV)
Wow & flutter	
Frequency response	10Hz to 20kHz (±1dB)
Total harmonic distortion	0.01% (1kHz)
Signal to noise ratio	
Dynamic range	96dB
Channel separation	85dB
FM tuner section	
Frequency range	87.9 to 107.9MHz [67R]
	87.5 to 108.0MHz [68R]
Channel space	200kHz [67R]
	50kHz [68R]

Usable sensitivity12.0dbf (1.1μV / 75Ω) 50dB quieting sensitivity15.2dbf (1.6μV / 75Ω) Frequency response30Hz to 15kHz (±1dB)

AM tuner section

Aivi tuner section	
Frequency range	530 to 1700kHz [67R]
	531 to 1611kHz [68R]
Channel space	10kHz [67R]
	9kHz [68R]
Usable sensitivity	27dbµ
Audio section	
	25 x 2 / 8 x 4W
Power output	15 x 2 / 5 x 4W
	(4Ω, 30~20kHz, 1% THD)
Tone action	
Bass	±8dB (100Hz)
Treble	±8dB (10kHz)
Preout level	1.0V
General	
Operating voltage	14.4V (11 to 16V)
Current consumption	5.0A
Operating temperature	10 to +50°C
Installation size	180 x 50 x170mm
	(7-1 / 16 x 1-15 / 16 x 6-11 / 16 inch)
\/\eight	1.2kg (2.6LBs)

KENWOOD follows a policy of continuous advancements in development. For this reason specifications may be changed without notice.

KENWOOD CORPORATION

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